



# Telespazio

A Finmeccanica/Thales Company

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## Architecture and Development Process of Spacecraft Simulators for ESOC

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Dr. Peter Fritzen

Telespazio VEGA Deutschland GmbH

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**27/05/2014**



## AGENDA

- ⇒ Telespazio VEGA Deutschland GmbH (VEGA)
  - ⇒ The Simulation, Navigation and Technology (SNT) Group
- ⇒ Satellite Missions of the European Space Agency (ESA)
  - ⇒ Mission Lifecycle and Phases
  - ⇒ Some recent example missions
  - ⇒ Role of the European Space Operations Centre (ESOC)
- ⇒ Architecture of a Spacecraft, and a Reference Architecture for Simulators
  - ⇒ High-Level Architecture of a Spacecraft
  - ⇒ Approach for a Reference Architecture to facilitate Model Re-Use
  - ⇒ Example of a specific instrument
- ⇒ Development Process of Operational Spacecraft Simulators
  - ⇒ Model Driven Architecture (MDA) for Design and Development
  - ⇒ Application Lifecycle Management (ALM) and Automation

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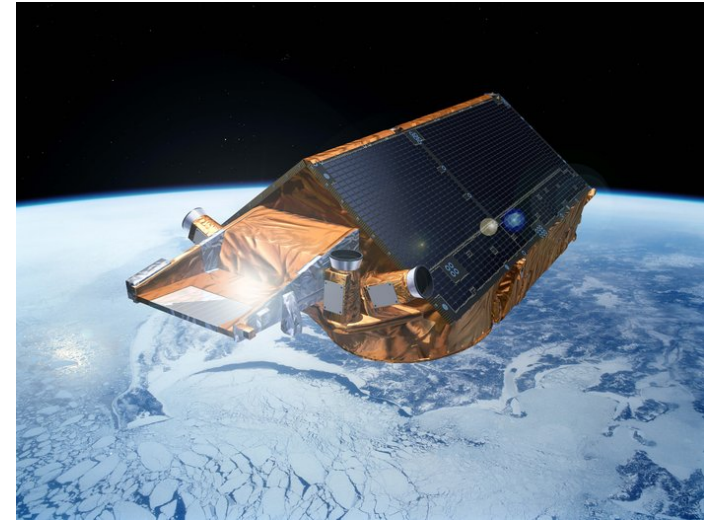
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## SOME EXAMPLE MISSIONS

- ✦ Earth Observation Missions
  - ✦ **CryoSat**: Are the Ice Caps shrinking?
    - ✦ Launched in April 2010
    - ✦ Still in Operations
    - ✦ Includes 3 Star Trackers
  - ✦ **Swarm**: Measure Earth Magnetic Field
    - ✦ Launched in November 2013
    - ✦ Just started Operations
    - ✦ Includes 2 Star Trackers
  - ✦ **EarthCare**: Clouds and Radiation
    - ✦ Launch scheduled for 2016



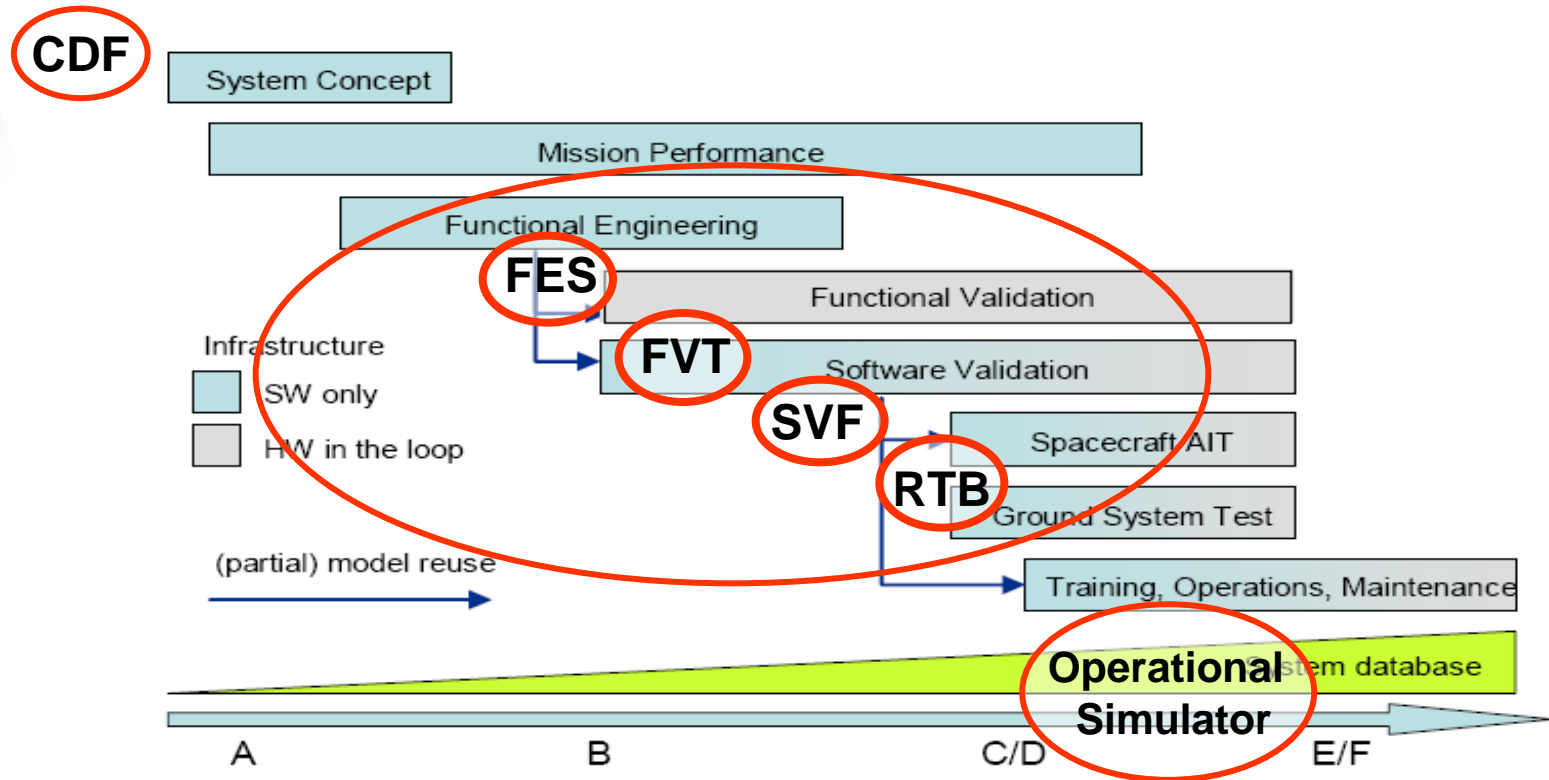


## SOME EXAMPLE MISSIONS

- ✧ Science Missions
  - ✧ **Rosetta**: The Comet Chaser
    - ✧ Launched in March 2004
    - ✧ Land on comet November 2014
    - ✧ Includes a Star Tracker
  - ✧ **Venus Express**: Explore Venus
    - ✧ Launched in November 2009
    - ✧ Science Operations just ended
    - ✧ Includes a Star Tracker
  - ✧ **Solar Orbiter**: Solar Physics
    - ✧ Launch scheduled for 2017



## ECSS-E-TM-10-21A: MODELLING & SIMULATION ENG. PROCESS



Model / Simulation Development

by ESA

by Industry

## **ROLE OF THE EUROPEAN SPACE OPERATIONS CENTRE (ESOC)**

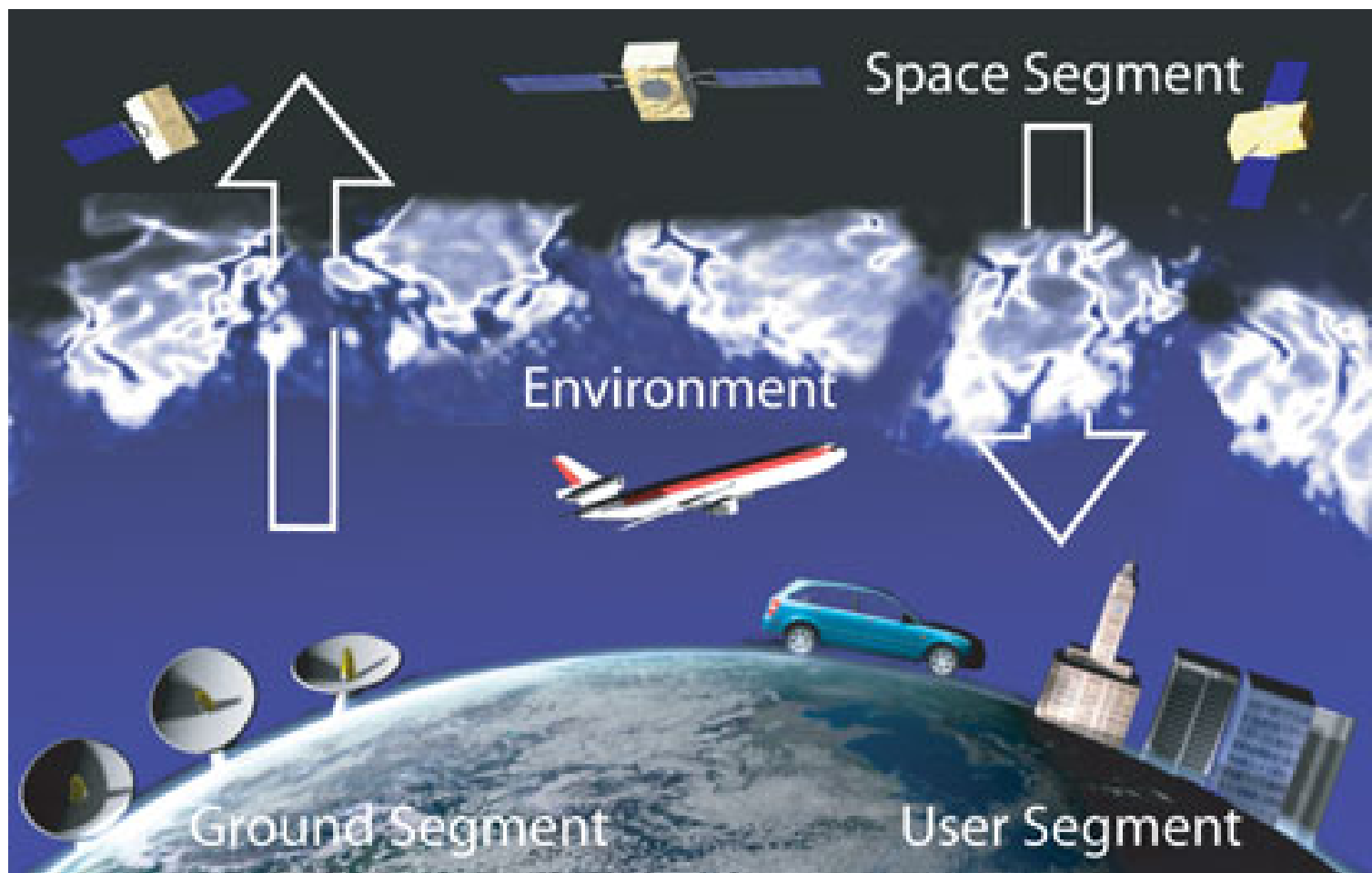
⇒ “Seconds after separation from the launcher – [...] – the spacecraft becomes the responsibility of the teams at ESOC.”

- ⇒ Mission Planning
- ⇒ Mission Operations
- ⇒ Mission Disposal





## ELEMENTS INVOLVED IN A SATELLITE MISSION



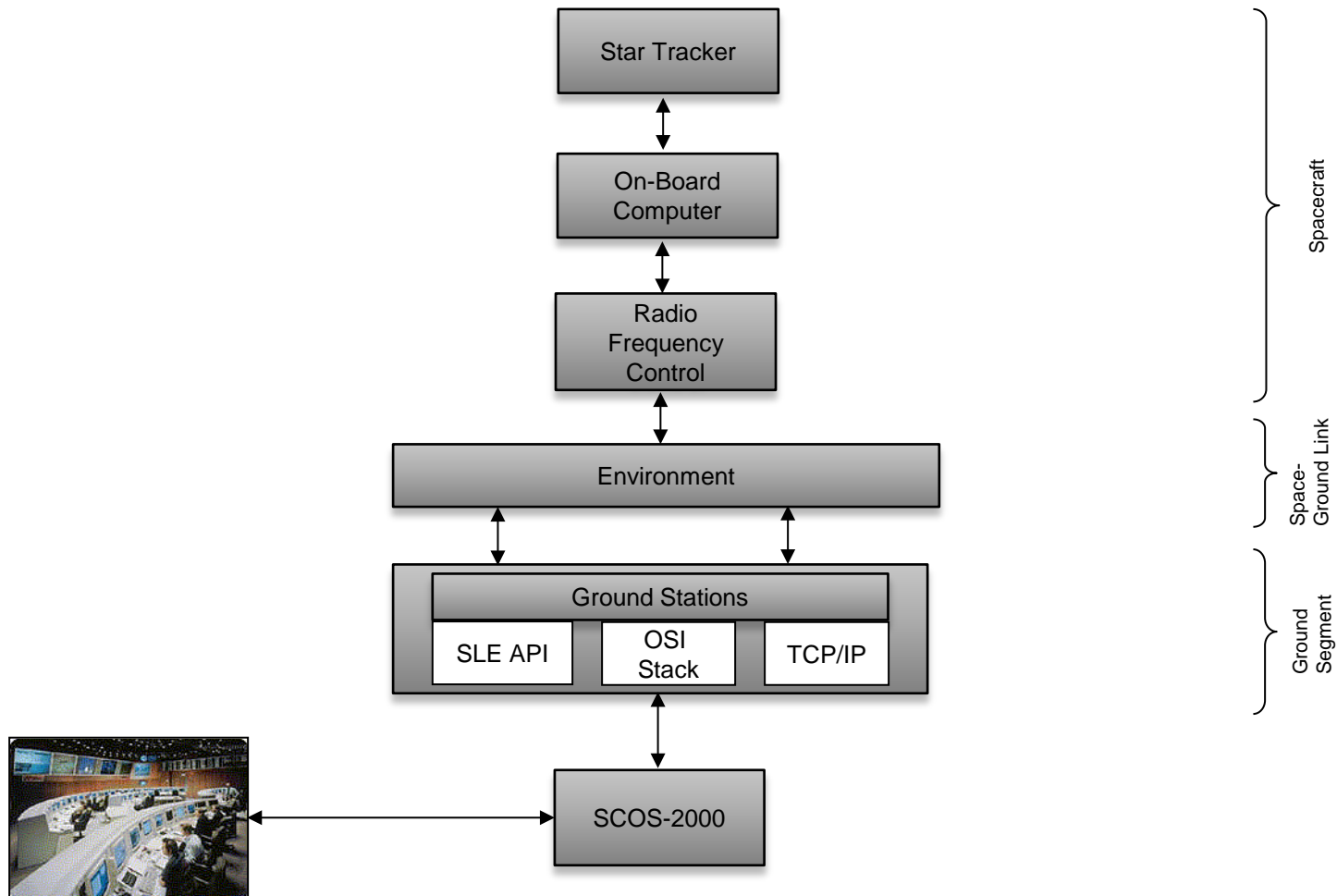
## INTERFACE BETWEEN ESOC AND A SPACECRAFT

- ⇒ ESOC Monitor a Spacecraft via **Telemetry**
  - ⇒ Telemetry is generated by each subsystems of the Spacecraft
  - ⇒ Telemetry is emitted by the Spacecraft to send data back to Earth
  - ⇒ Telemetry is received by a Ground Station Receiver
  - ⇒ Telemetry is visualised using the Satellite Control and Operation System (**SCOS**)
  
- ⇒ ESOC Control a Spacecraft via **Telecommands**
  - ⇒ Telecommands are assembled by a Spacecraft Controller via SCOS
  - ⇒ Telecommands are transmitted by a Ground Station Transmitter
  - ⇒ Telecommands are received by the Spacecraft
  - ⇒ Telecommands are (typically) processed by the On-Board Computer

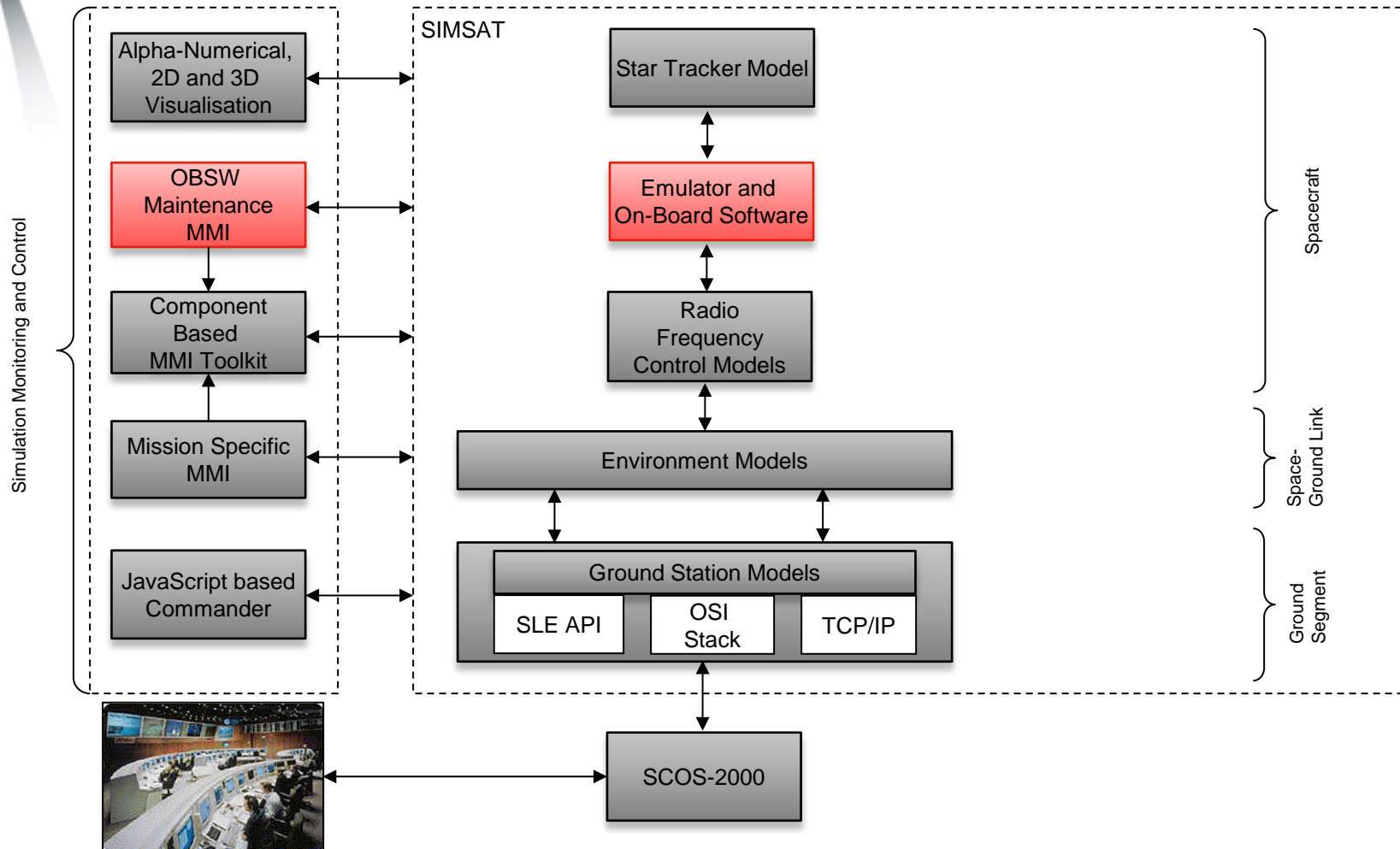
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## DATA FLOW BETWEEN ESOC AND A STAR TRACKER



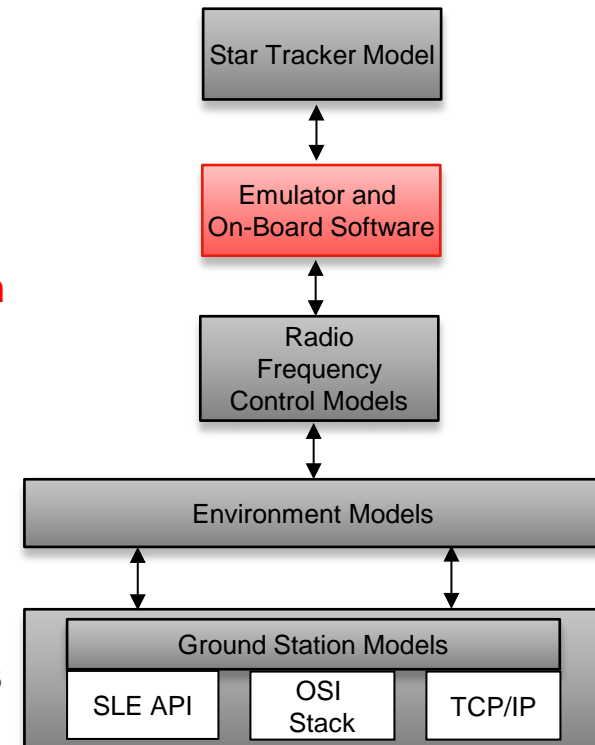
## DATA FLOW BETWEEN ESOC AND A STAR TRACKER MODEL





## APPROACH FOR SPACECRAFT SIMULATION

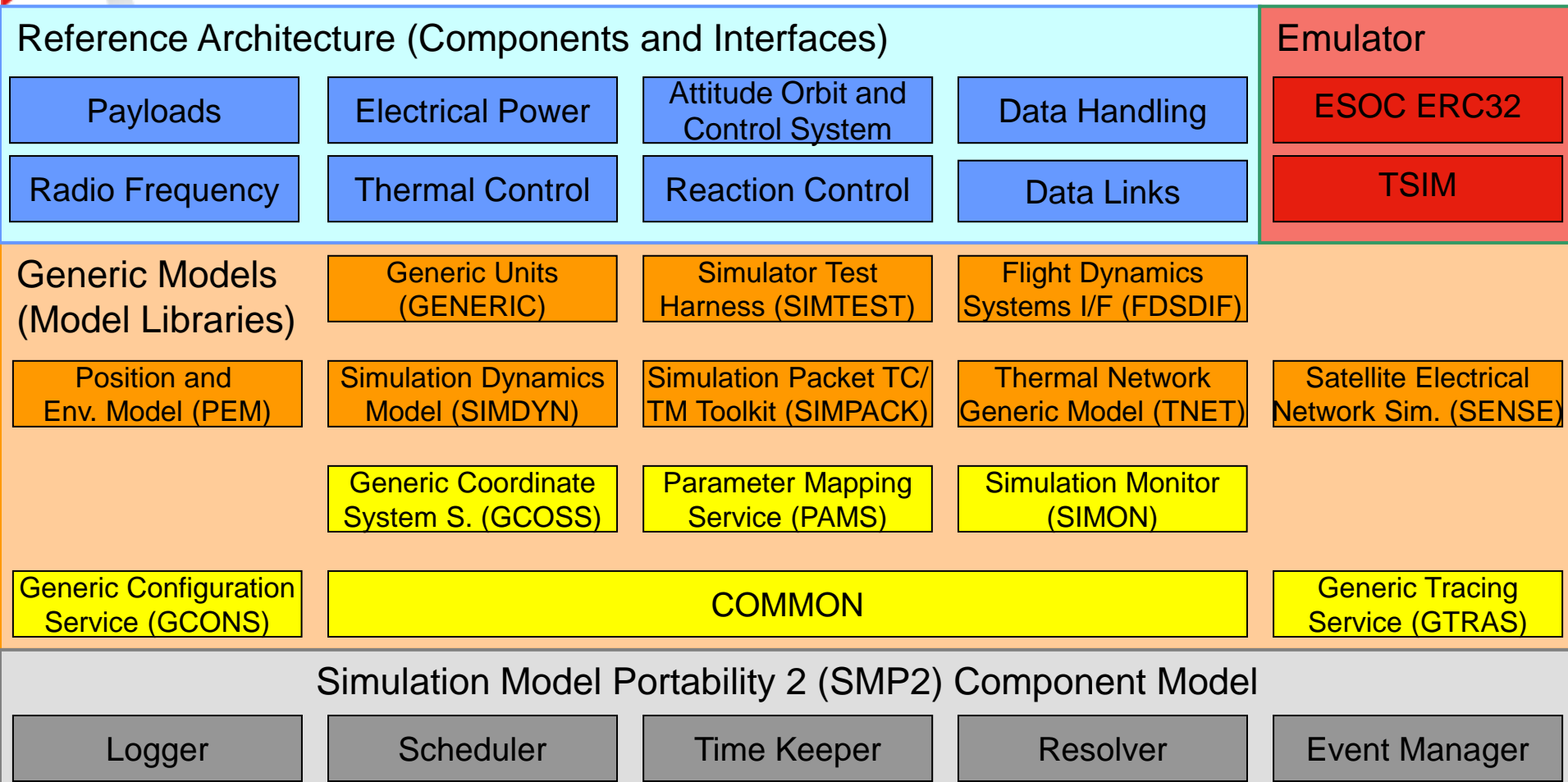
- ⇒ For all Spacecraft Subsystems, a Reference Architecture (REFA) has been established
- ⇒ Architecture defines common components and interfaces between them
- ⇒ Architecture makes use of common libraries
- ⇒ **The On-Board Software is used from the Mission**
- ⇒ The Emulator is generic (per Processor) and can be re-used across missions
- ⇒ The Environment Models are implemented as a Library which can be configured per Mission
- ⇒ Ground Station Models are independent of a specific S/C and can be re-used across missions



## THE SPACECRAFT SIMULATOR REFERENCE ARCHITECTURE

- ⇒ Defines a reference architecture for operational simulators for ESOC.
- ⇒ Defines standard interfaces between common satellite subsystems' models
- ⇒ Used within ESOC's UML modelling framework (UMF)
- ⇒ Strongly based on ESOC's Generic Models (GENM) Libraries
- ⇒ Promotes consistency in design across the different mission simulators  
→ **facilitates re-use of design and models.**
- ⇒ No model implementation provided – design only.
- ⇒ Can be extended to meet a particular mission simulator needs.
- ⇒ Mission changes may feed back into the maintained REFA.

## REFERENCE ARCHITECTURE (REFA) AND GENERIC MODELS



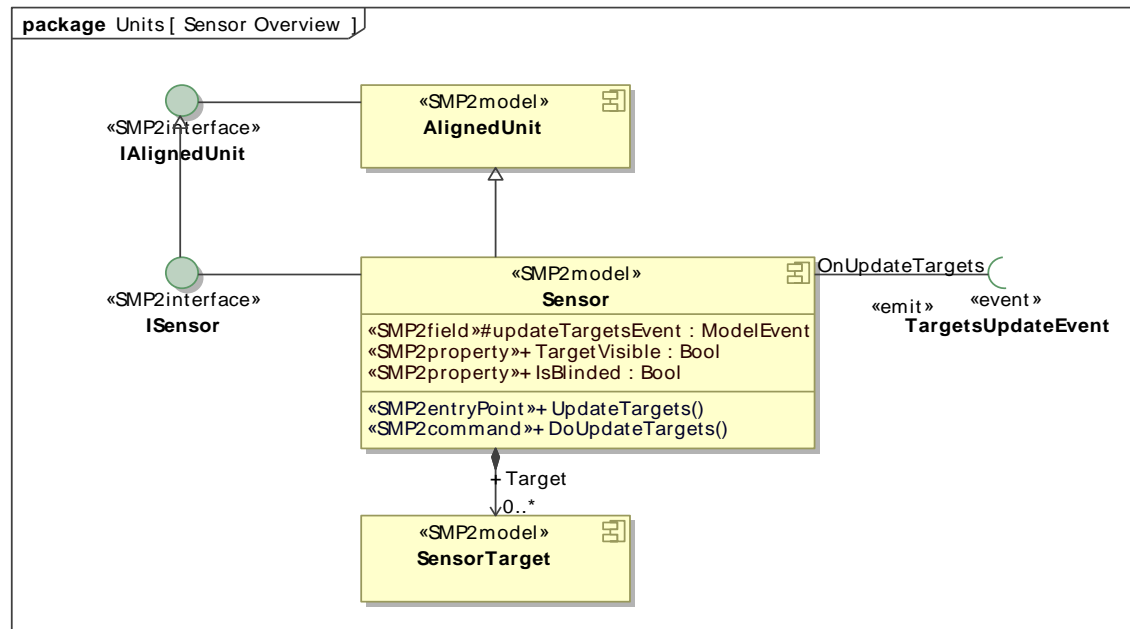
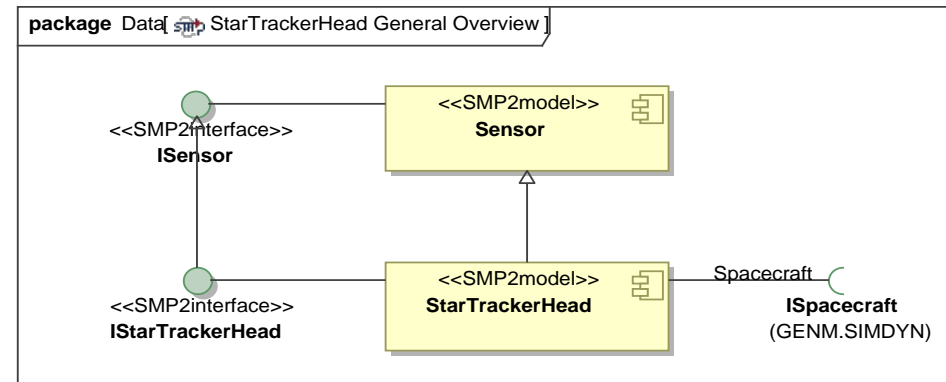
## REFA SUBSYSTEMS

⇒ The Reference Architecture covers the following subsystems

- ⇒ AOCS      Attitude and Orbital Control System
- ⇒ DHS      Data Handling System
- ⇒ DL        Data Links
- ⇒ EPS      Electrical Power System
- ⇒ RCS      Reaction Control System
- ⇒ RFCS     Radio Frequency Control System
- ⇒ TCS      Thermal Control System
- ⇒ PL        Payloads (only generic architecture)

## REFA EXAMPLE – THE STAR TRACKER HEAD ARCHITECTURE

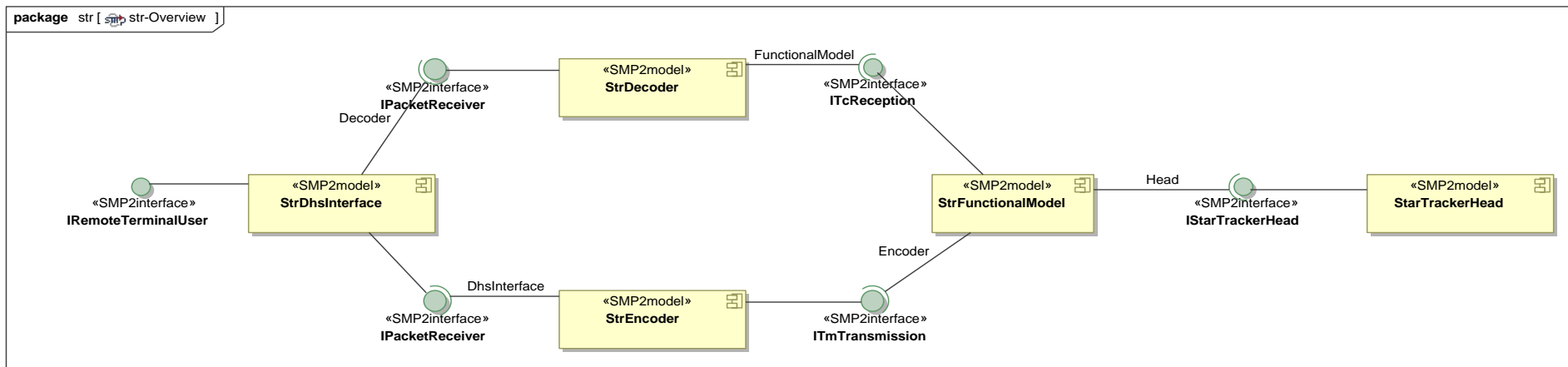
- REFA defines interfaces and “abstract” models for design
- These models make use of GENM interfaces and model libraries
- GENM libraries provide fully tested code for common cases
- Missions need to “complete” their implementation by deriving from REFA





## REFA EXAMPLE – THE COMPLETE STAR TRACKER

- ✦ Complete Star Tracker (**STR**) design includes various other elements
  - ✦ The STR communicates with the On-Board Computer via a Bus
  - ✦ The STR decodes **Telecommands** and encodes **Telemetry**
  - ✦ The STR implements a Functional Model (complex state machine)
  - ✦ The STR receives Measurements from the Star Tracker Head



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## TECHNICAL CHALLENGES

- ⇒ Accurate Modelling of highly complex System
  - ⇒ High focus on formal testing and validation
  
- ⇒ Demanding Requirements on Documentation
  - ⇒ European Commission for Space Standardisation (**ECSS**)
  
- ⇒ Long-Term Maintenance until End of Mission
  - ⇒ Typically requires migration to new platform/operating system
  
- ⇒ Distributed Development Team
  - ⇒ Fully integrated development environment across countries

## RECENT TECHNOLOGIES

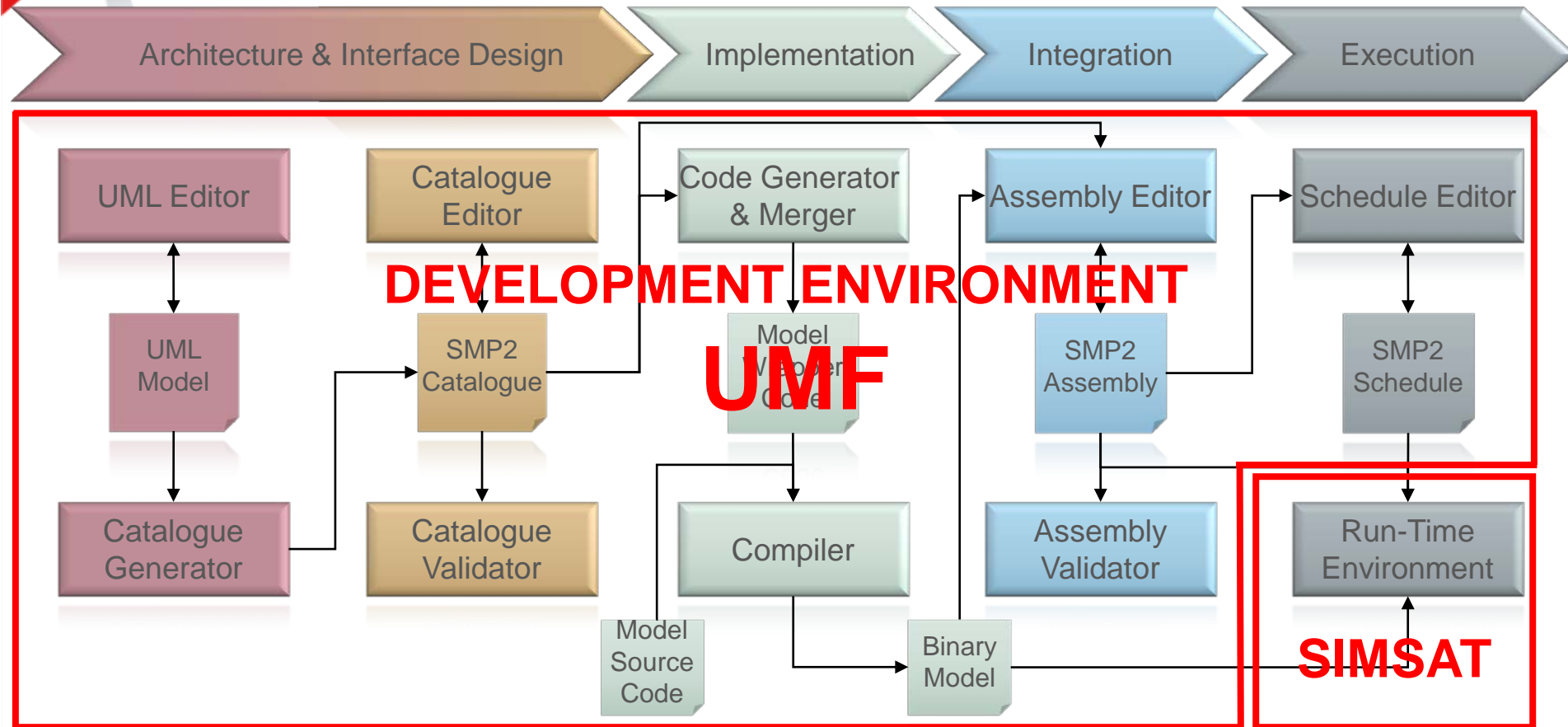
- ⇒ Full Automation of Testing
  - ⇒ Unit and Integration Testing is done via CppUnit / JUnit
  - ⇒ System Testing is done via JavaScript procedures (Scripting Language)
  - ⇒ All Tests are executed every night (“nightly build and test approach”)
- ⇒ Apply Model Driven Architecture (**MDA**) based development approach
  - ⇒ Complete system is modelled in Universal Modelling Language (**UML**)
  - ⇒ Source code is generated from UML Design
  - ⇒ Documentation is generated from UML Design
- ⇒ Strict Adherence to Open Standards
  - ⇒ Avoid dependency on a specific Platform, Operation System or Tool
  - ⇒ Use Static Code Analysis to detect platform specific code
  - ⇒ Build and Test on various Operating Systems (LINUX, Windows)

## MODEL DRIVEN ARCHITECTURE APPROACH FOR SIMULATORS

- ⇒ As a common simulation platform, a simulation standard has been defined
  - ⇒ **SMP2** is the Simulation Model Portability Standard by ESA
  - ⇒ **SMP** is the Simulation Modelling Platform Standard by ECSS
- ⇒ To support MDA, a Domain Specific Language (**DSL**) has been defined
  - ⇒ The Simulation Model Definition Language (**SMDL**) is part of SMP2
  - ⇒ An Implementation of SMDL in a commercial UML tool is available
  - ⇒ Tools to generate Documentation from SMDL have been developed
  - ⇒ Tools to generate C++ Source Code from SMDL have been developed
- ⇒ All Generic Models (GENM) have been migrated to SMDL and SMP2
- ⇒ The Reference Architecture (REFA) has been defined using SMDL

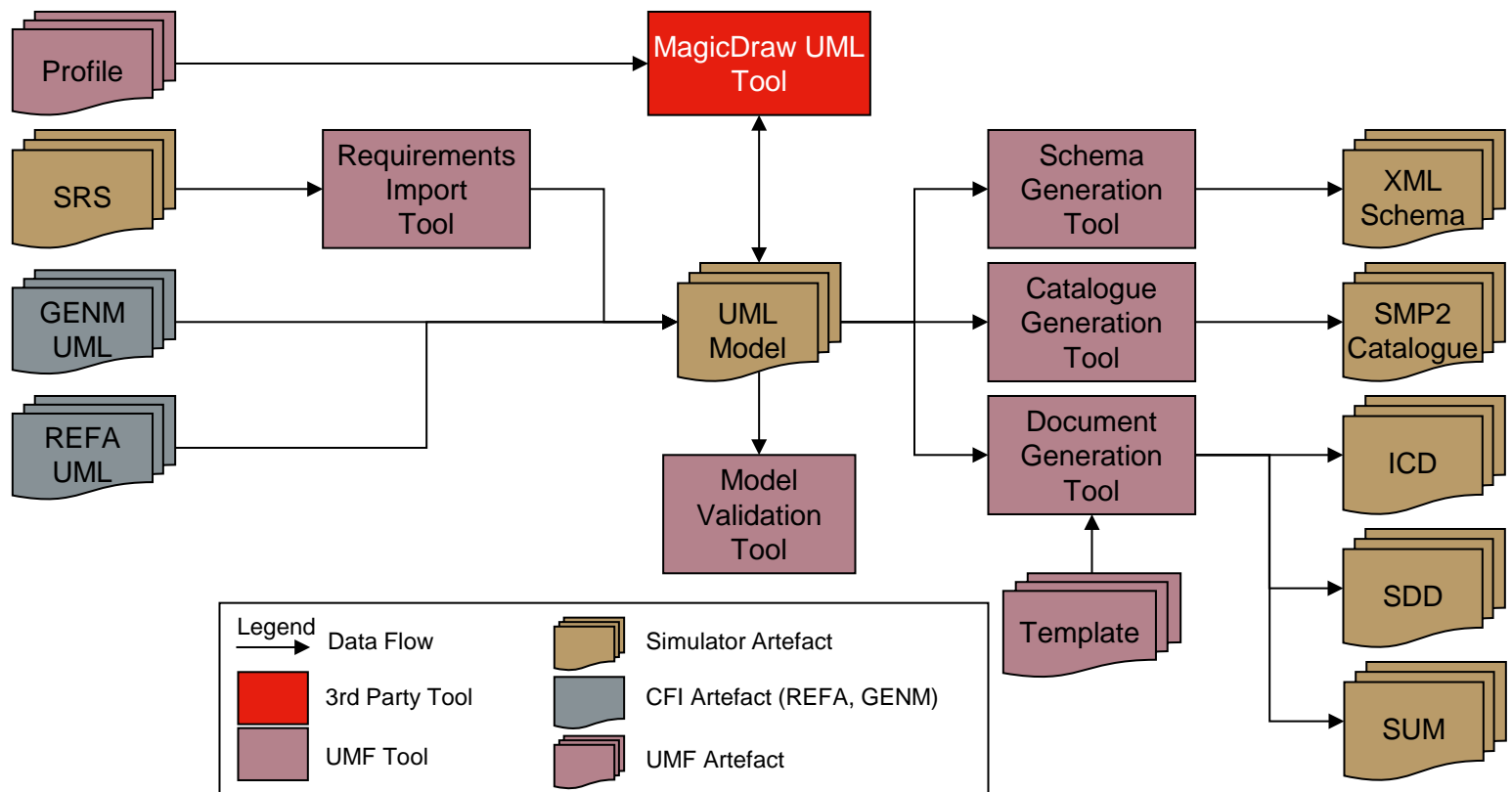


## SMDL SIMULATION DEVELOPMENT LIFE-CYCLE AND TOOLS



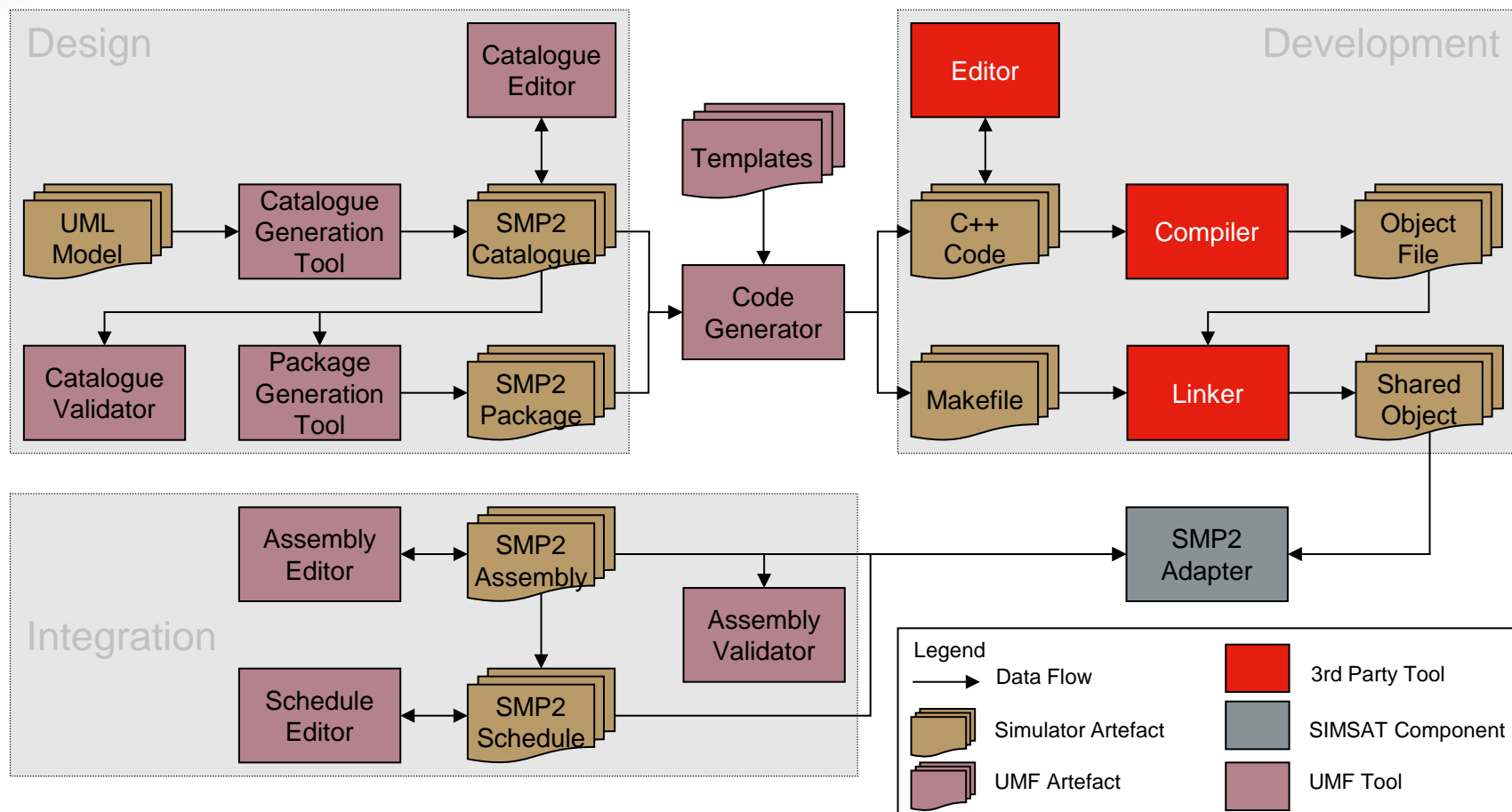
## SMDL MODEL DRIVEN DESIGN PROCESS

Usage of UMF Tools in the context of SMDL Model Driven Design (MDD)



# SMDL MODEL DRIVEN SOFTWARE DEVELOPMENT USING SMDL

## Usage of UMF Tools in the context of SMDL Model Driven Software Development



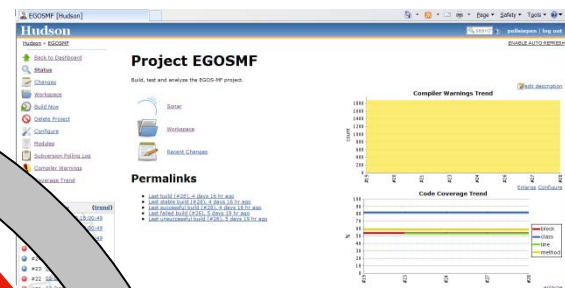
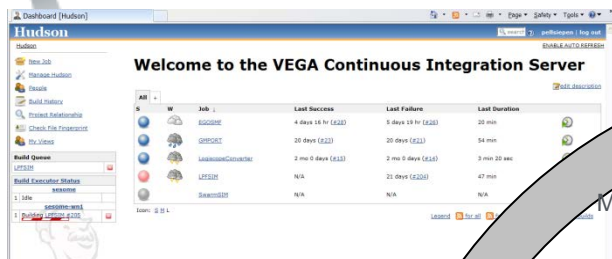
## PROCESS OBJECTIVES

- ⇒ Reduce Development Cost
- ⇒ Increase Number of Deliveries (“Incremental” or “Agile” approach)
- ⇒ Compress Schedule
- ⇒ Provide Transparency of current Status
- ⇒ Subcontract at least 40% of the Development to a Qualified Partner (QPA)
- ⇒ Share Hardware Resources between Missions

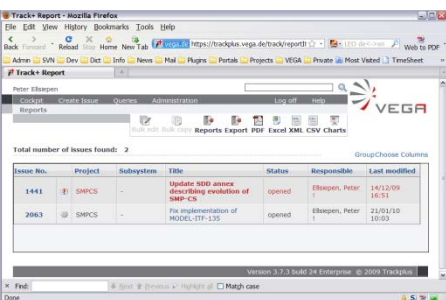
# APPLICATION LIFECYCLE MANAGEMENT (ALM)

Continuous Integration

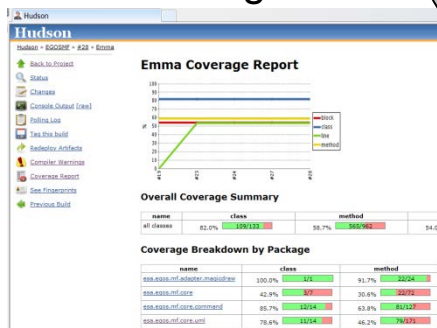
Project Dashboard



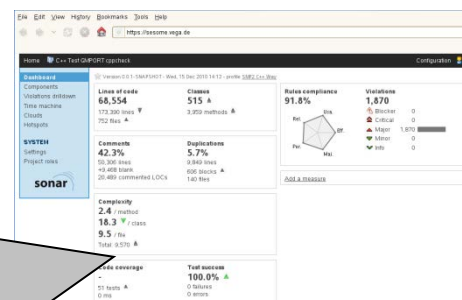
Issue Tracking



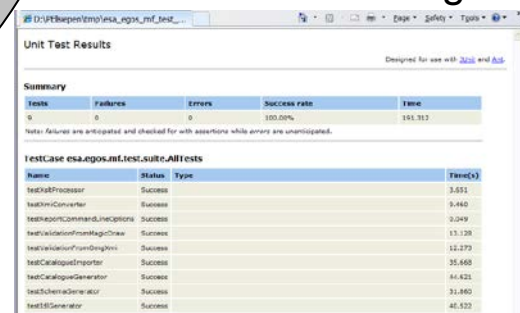
Test Coverage



Rules & Metrics



Automated Testing

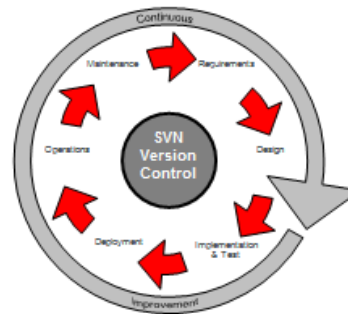






# SYSTEM ENGINEERING AND SOFTWARE MANAGEMENT ENV.

## SESOME

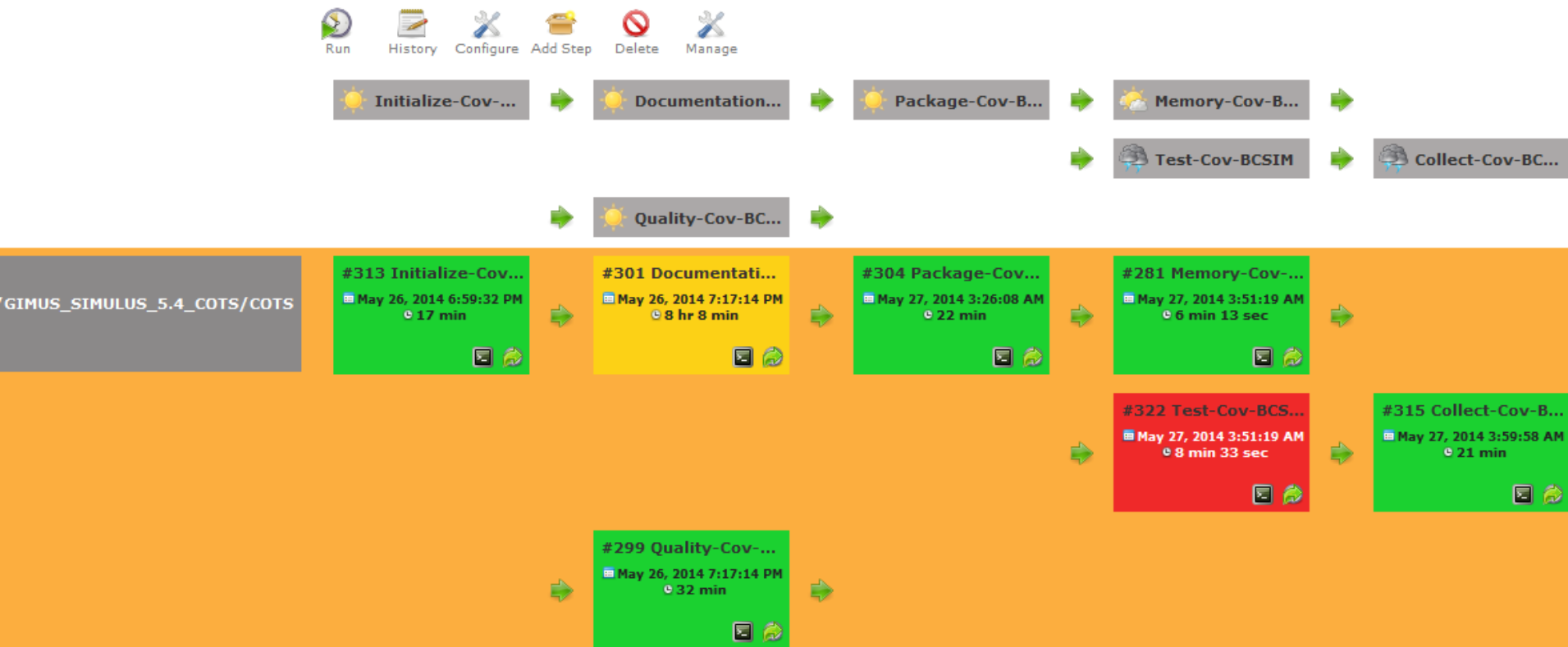
The Telespazio VEGA System Engineering and Software Management Environment



Application	Purpose	URL
 <b>Jenkins</b>	Continuous Integration	<a href="https://sesome.telespazio-vega.de/jenkins">https://sesome.telespazio-vega.de/jenkins</a> <a href="https://sesome.telespazio-vega.de/hudson">https://sesome.telespazio-vega.de/hudson</a>
 <b>sonarqube</b>	Quality and Metrics	<a href="https://sesome.telespazio-vega.de/sonarqube">https://sesome.telespazio-vega.de/sonarqube</a> <a href="https://sesome.telespazio-vega.de/sonar">https://sesome.telespazio-vega.de/sonar</a> (old)
	Repository Browsing	<a href="https://svn.telespazio-vega.de/viewvc">https://svn.telespazio-vega.de/viewvc</a>
	Repository Access	Example for "sample" repository: <a href="https://svn.telespazio-vega.de/svn/sample">https://svn.telespazio-vega.de/svn/sample</a>
	Issues and Tasks	<a href="https://jira.telespazio-vega.de/">https://jira.telespazio-vega.de/</a>

# JENKINS

## Coverage Pipeline



# VALGRIND

Jenkins

?
[pfritzen](#) | [log out](#)

[Jenkins](#)
[TPZV](#)
[SNT](#)
[EXMSIM](#)
[EXMSIM Coverage Pipeline](#)
[Memory-Cov-EXMSIM](#)
[#144](#)

[Back to Project](#)
[Status](#)
[Changes](#)
[Console Output](#)
[Edit Build Information](#)
[Delete Build](#)
[Parameters](#)
[Tag this build](#)
[See Fingerprints](#)
[Valgrind Result](#)
[Failure Cause Management](#)
[Downstream build view](#)
[Build Artifacts As Maven Repository](#)
[Build Graph](#)

## Valgrind Result (Processes Overview)

Process	Parent	Errors	Bytes Leaked
<a href="#">esa.exmsim.assemblies.itest (19156)</a>	16624	Leak (definitely lost) 3 Uninitialized Condition 11	Definitely Lost 17125408
<a href="#">esa.exmsim.eps.itest (24779)</a>	16624		
<a href="#">esa.exmsim.eps.itest (25109)</a>	16624	Uninitialized Condition 27	
<a href="#">esa.exmsim.eps.itest (24258)</a>	16624		
<a href="#">esa.exmsim.eps.itest (24709)</a>	16624	Uninitialized Condition 2	
<a href="#">esa.exmsim.eps.itest (2476)</a>	16624		
<a href="#">esa.exmsim.eps.itest (2631)</a>	16624		
<a href="#">esa.exmsim.eps.itest (23146)</a>	16624		
<a href="#">esa.exmsim.eps.pcu.utest (23429)</a>	16624		
<a href="#">esa.exmsim.qeneric.utest (16651)</a>	16624		
<a href="#">esa.exmsim.qnc.css.itest (23530)</a>	16624		
<a href="#">esa.exmsim.qnc.css.utest (16740)</a>	16624	Leak (definitely lost) 3	Definitely Lost 5252
<a href="#">esa.exmsim.qnc.imu.itest (21554)</a>	16624		
<a href="#">esa.exmsim.qnc.imu.utest (16786)</a>	16624	Leak (definitely lost) 2	Definitely Lost 3990


# SONARCUBE

Home

TOOLS

Dependencies



Compare



[My favourites](#)






A	Name ^	Last Analysis
No data		

[Projects in error](#)

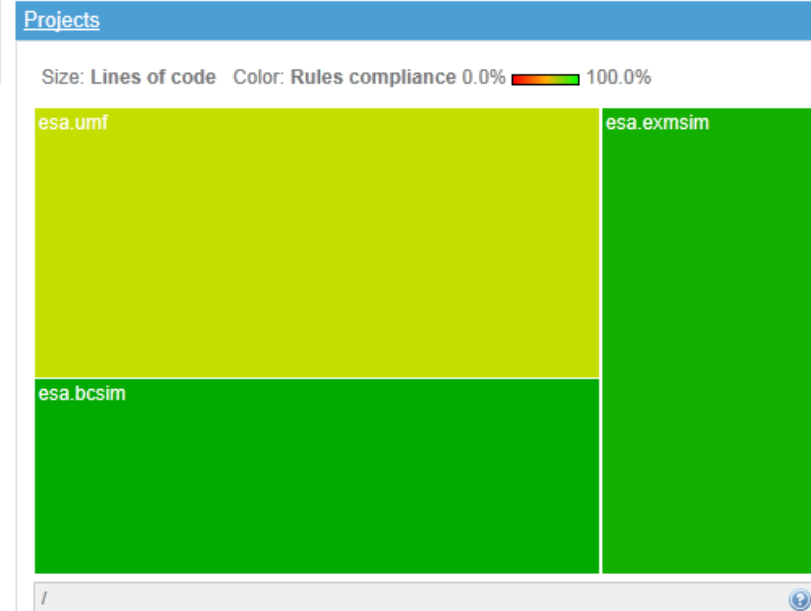
A	Name ^	Blocker issues	UTs failures	UTs errors	Last Analysis
☆ !	 <a href="#">esa_bcsim</a>	0	4 	0	04:12

1 results

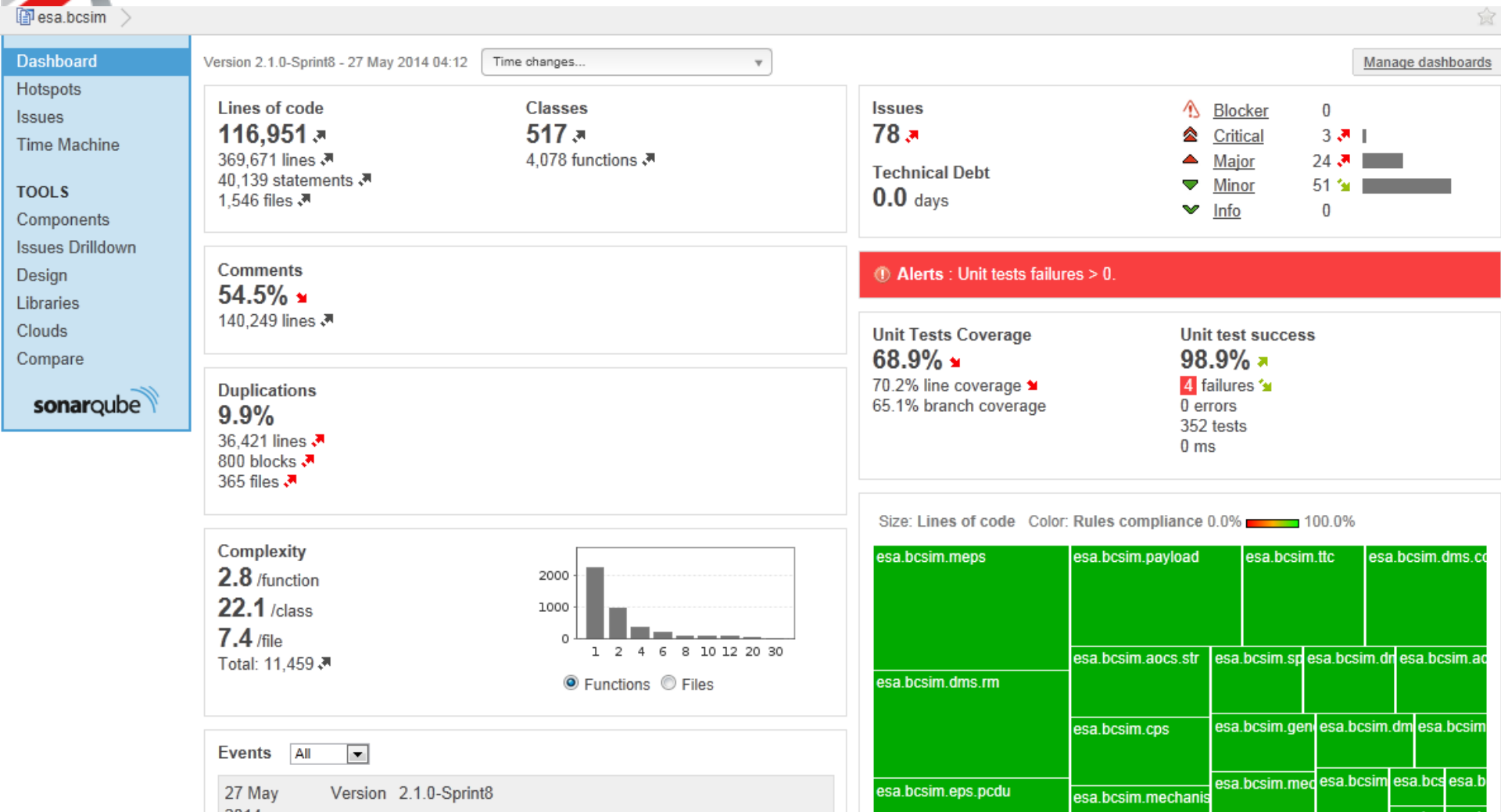
[Projects](#) [Manage dashboards](#)

A	Name ^	Version	LOCs	RCI	Last Analysis
☆ !	 <a href="#">esa_bcsim</a>	2.1.0-Sprint8	116,951 	99.9%	04:12
☆ ✓	 <a href="#">esa_exmsim</a>	1.0.0-Sprint3	107,587 	96.2%	07:06
☆	 <a href="#">esa_umf</a>	2.0.2-SNAPSHOT	159,465	61.6%	09 May 2014

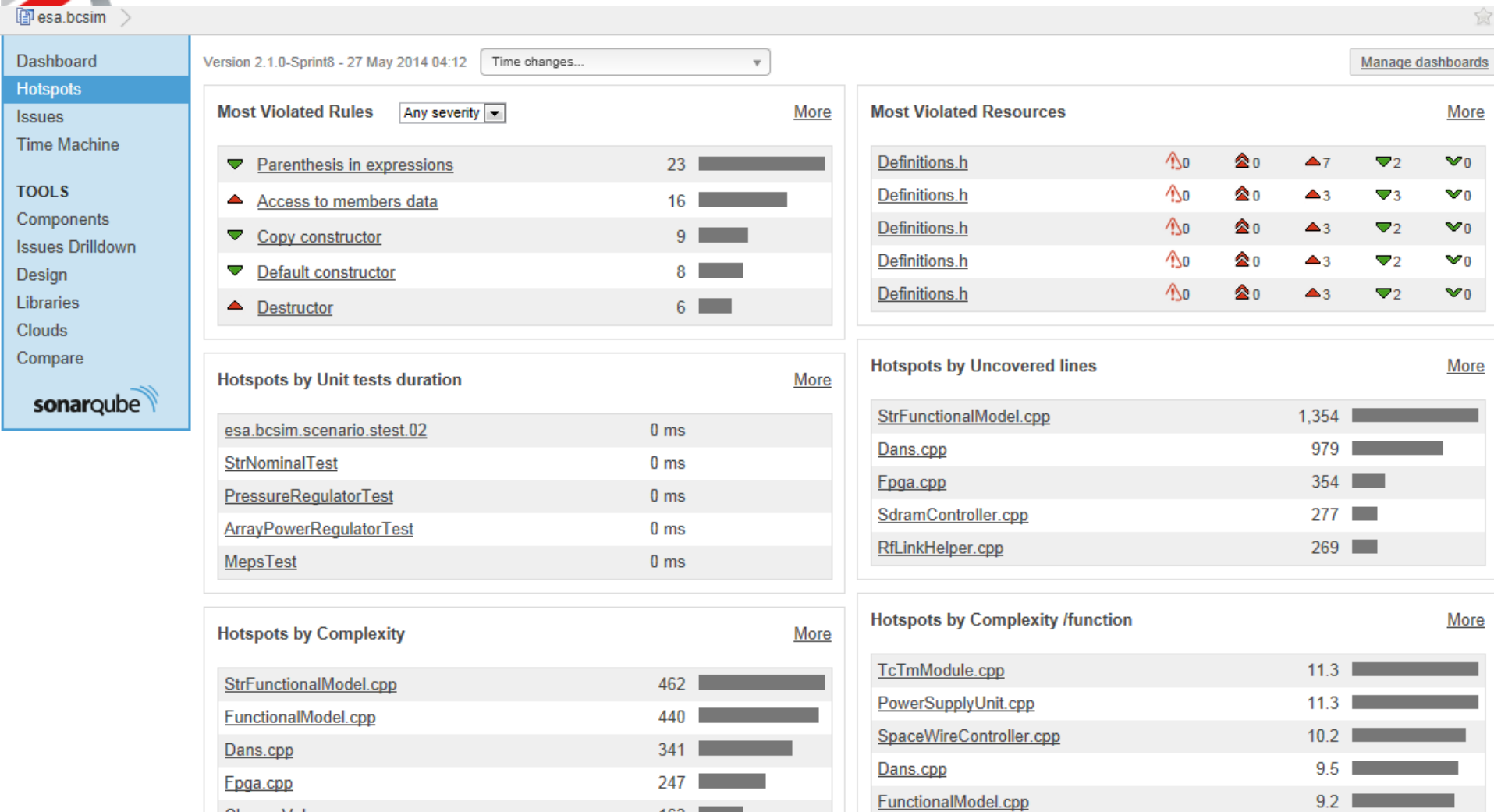
3 results



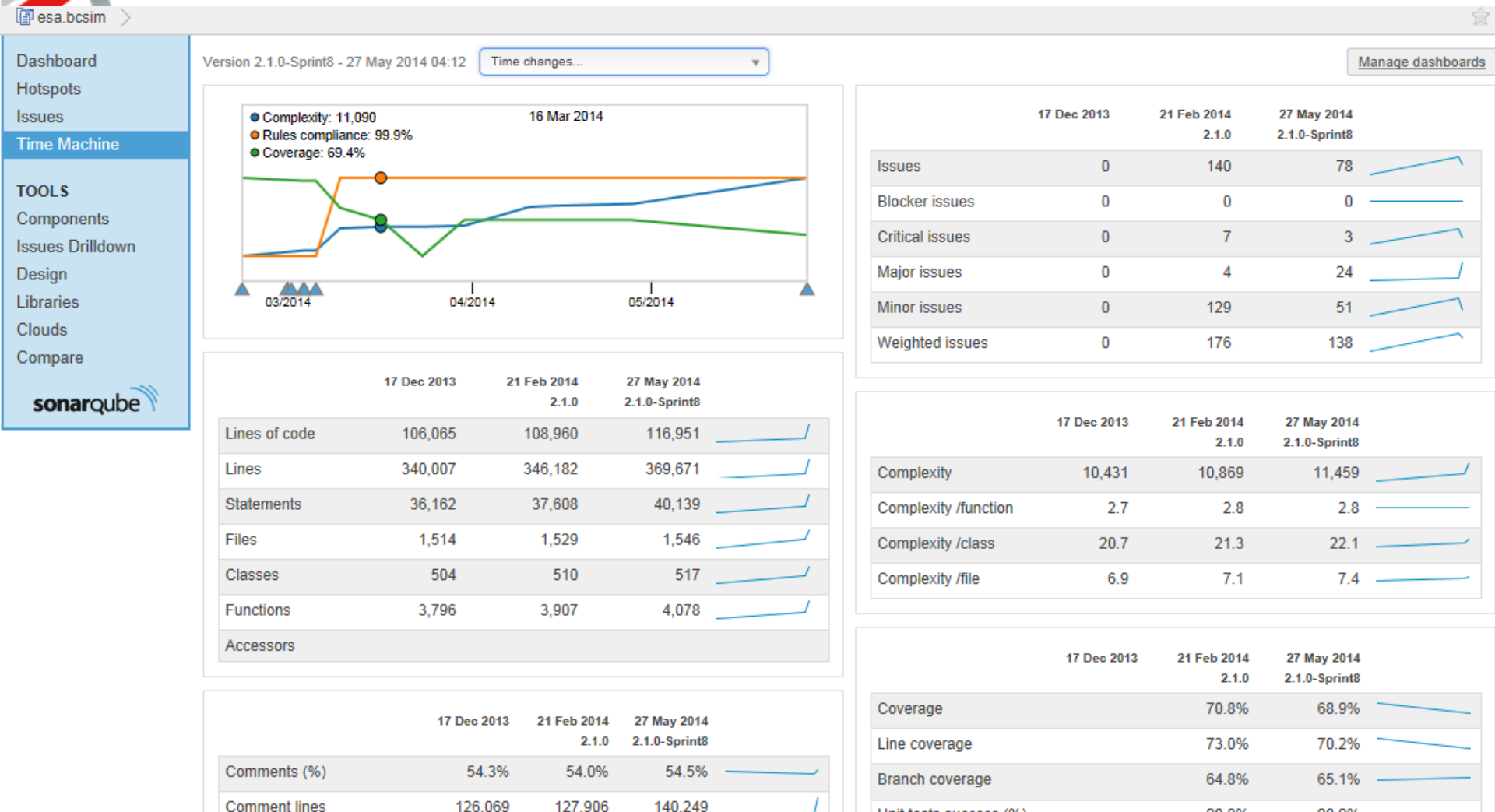
# DASHBOARD



# HOTSPOTS



# TIME MACHINE



# COMPONENTS

esa.bcsim >

Dashboard

Hotspots

Issues

Time Machine

TOOLS

Components

Issues Drilldown

Design

Libraries

Clouds

Compare

sonarqube

!

☆

esa.bcsim

99.9%

68.9%

04:12

☆

🔍

esa.bcsim.aocs.fss

100.0%

92.5%

04:12

☆

🔍

esa.bcsim.assemblies

100.0%

85.5%

04:12

☆

🔍

esa.bcsim.ttc

99.8%

83.1%

04:12

☆

🔍

esa.bcsim.eps.bat

100.0%

82.5%

04:12

☆

🔍

esa.bcsim.aocs.rwl

99.9%

78.8%

04:12

☆

🔍

esa.bcsim.eps.sa

99.8%

78.1%

04:12

☆

🔍

esa.bcsim.cps

100.0%

78.0%

04:12

☆

🔍

esa.bcsim.aocs.imu

99.8%

76.9%

04:12

☆

🔍

esa.bcsim.dms.tctm

100.0%

75.5%

04:12

☆

🔍

esa.bcsim.mechanisms.magboom

100.0%

74.6%

04:12

☆

🔍

esa.bcsim.eps.pcd

99.8%

74.6%

04:12

☆

🔍

esa.bcsim.dms.smm

100.0%

74.0%

04:12

☆

🔍

esa.bcsim.tcs

99.9%

73.7%

04:12

☆

🔍

esa.bcsim.dms.rm

100.0%

73.1%

04:12

☆

🔍

esa.bcsim.generic

100.0%

69.3%

04:12

☆

🔍

esa.bcsim.dms.common

100.0%

69.2%

04:12

☆

🔍

esa.bcsim.dms.riu

100.0%

69.1%

04:12

☆

🔍

esa.bcsim.datalinks

100.0%

67.7%

04:12



# ISSUES DRILLDOWN

esa.bcsim

Dashboard

Hotspots

Issues

Time Machine

TOOLS

Components

Issues Drilldown

Design

Libraries

Clouds

Compare

sonarqube

Profile Sonar way with Logiscope

Time changes...

Severity

Blocker 0

Critical 3

Major 24

Minor 51

Info 0

Rule

All variables must be initialized before being used 2

Pointer initialization 1

Access to members data 16

Destructor 6

Prefer C++-style casts 1

Try blocks in destructors 1

esa.bcsim.eps.pcd

16

esa.bcsim.mechanisms.sada

15

esa.bcsim.mechanisms.apme

12

esa.bcsim.ttc

8

esa.bcsim.meps

8

esa.bcsim.eps.sa

7

esa/bcsim/eps/pcdu/mpo

11

esa/bcsim/mechanisms/sada/mpo

10

esa/bcsim/meps

8

esa/bcsim/ttc

8

esa/bcsim/mechanisms/apme/hgama

6

esa/bcsim/eps/pcdu/mtm

5

Definitions.h

9

Definitions.h

6

Definitions.h

5

Definitions.h

5

Definitions.h

5

Definitions.h

5

Se.

Status

Description

Component

Assignee

Action plan

Updated

Open

writeValue = static\_cast<Smp::UInt16>(( buffer[itRegister] ) & 0xFFFF)

esa.bcsim  
esa/bcsim/dms/rm/MemoryLogicBase.cpp

26 Apr 2014

Open

(( breakwireExecuted == false ) && ( enabled == true ) && ( breakwireEvent.ge...

esa.bcsim  
esa/bcsim/eps/pcdu/mpo/Dplm.cpp

04:12

Open

(( i < ( static\_cast<Smp::Int64>(MPO\_FPGA\_EEPROM\_BYTE\_SIZE) / 2 ) ) && (...

esa.bcsim  
esa/bcsim/eps/pcdu/mpo/Fpga.cpp

04:12

Open

block.get\_Data()[0 + k \* 2] = static\_cast<Smp::Int8>(buffer[k] & 0xFF)

esa.bcsim  
esa/bcsim/eps/pcdu/mpo/Fpga.cpp

03 Mar 2014

Open

DplmSelection

esa.bcsim

03 Mar 2014

27/05/2014

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# SUBVERSION

[bcsim] / trunk / Src

/trunk/Src

 r3764

File	Rev.	Age	Author	Last log entry
 ..				
 esa.bcsim/	3673	6 weeks	pellsiepen	sim#2033 simul5#119: Updated solution Makefile and associated template such th...
 esa.bcsim.aocs/	3617	2 months	dsegneri	Merged SIMULUS_5.4 branch into trunk
 esa.bcsim.aocs.fss/	3617	2 months	dsegneri	Merged SIMULUS_5.4 branch into trunk
 esa.bcsim.aocs.imu/	3759	7 days	fmatera	IMU-FCE integration improved
 esa.bcsim.aocs.rwl/	3722	3 weeks	dsegneri	Change needed to be compatible with two REFA versions
 esa.bcsim.aocs.str/	3693	6 weeks	fmatera	Initialization of STR power on state updated in StrFunctionalModel
 esa.bcsim.assemblies/	3731	2 weeks	clourenco	BepiSIM#306: Added a switchWhileOff bool field which, when true, allows the TSW ...
 esa.bcsim.configurations/	37	View directory revision log		IMU-FCE integration improved
 esa.bcsim.cps/	3713	4 weeks	clourenco	Moved Thruster's lastUpdateTime and firingUpdateEventId fields into the model. A...
 esa.bcsim.datalinks/	3720	3 weeks	ezanatta	Corrected non compliances to coding standard rules from Format Checker
 esa.bcsim.dms/	3720	3 weeks	ezanatta	Corrected non compliances to coding standard rules from Format Checker
 esa.bcsim.dms.common/	3738	2 weeks	dsegneri	Provided fix for SPR BepiSIM#275. Design needs to be updated and test implemente...
 esa.bcsim.dms.fce/	3720	3 weeks	ezanatta	Corrected non compliances to coding standard rules from Format Checker
 esa.bcsim.dms.obc/	3720	3 weeks	ezanatta	Corrected non compliances to coding standard rules from Format Checker
 esa.bcsim.dms.pm/	3721	3 weeks	mirvine	Add UART2 register used by OBSW during boot (but UART2 not used during run of ap...

## REFERENCES

- ⇒ Some images have been taken from [www.esa.int](http://www.esa.int) and are Copyright by ESA
- ⇒ Some information has been taken from [www.wikipedia.org](http://www.wikipedia.org)



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