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**Architecture and Development Process** of Spacecraft Simulators for ESOC

Dr. Peter Fritzen

Telespazio VEGA Deutschland GmbH

27/05/2014

### AGENDA

elespazio

hales Company

- Telespazio VEGA Deutschland GmbH (VEGA)
  - The Simulation, Navigation and Technology (SNT) Group
- ⇒ Satellite Missions of the European Space Agency (ESA)
  - ✤ Mission Lifecycle and Phases
  - ✤ Some recent example missions
  - ⇒ Role of the European Space Operations Centre (ESOC)
- ⇒ Architecture of a Spacecraft, and a Reference Architecture for Simulators
  - High-Level Architecture of a Spacecraft
  - ⇒ Approach for a Reference Architecture to facilitate Model Re-Use
  - ✤ Example of a specific instrument
- Development Process of Operational Spacecraft Simulators
  - Model Driven Architecture (MDA) for Design and Development
  - ⇒ Application Lifecycle Management (ALM) and Automation

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Introduction



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Introduction



Satellite Missions of the European Space Agency

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Satellite Missions of the European Space Agency

### SOME EXAMPLE MISSIONS

- Earth Observation Missions
  - CryoSat: Are the Ice Caps shrinking?
    - Launched in April 2010
    - Still in Operations
    - Includes 3 Star Trackers
  - Swarm: Measure Earth Magnetic Field
    - Launched in November 2013

    - ✤ Includes 2 Star Trackers
  - **EarthCare**: Clouds and Radiation
    - ✤ Launch scheduled for 2016







#### Satellite Missions of the European Space Agency

### SOME EXAMPLE MISSIONS

- - Rosetta: The Comet Chaser
    - ⇒ Launched in March 2004
    - Land on comet November 2014
    - ✤ Includes a Star Tracker

#### ⇒ Venus Express: Explore Venus

- Launched in November 2009
- Science Operations just ended
- Includes a Star Tracker
- Solar Orbiter: Solar Physics
  - ✤ Launch scheduled for 2017

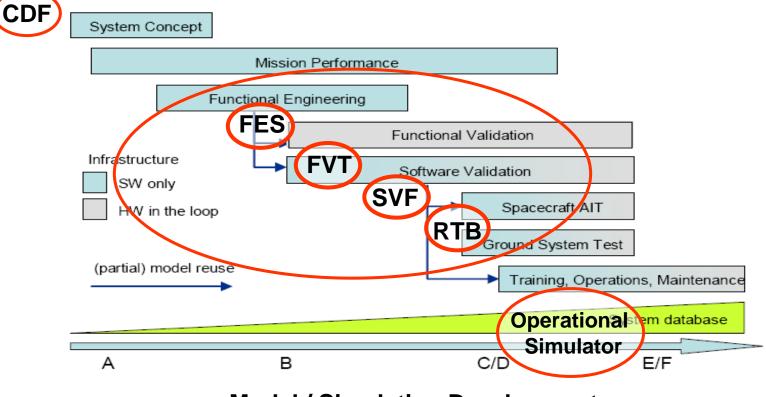






Satellite Missions of the European Space Agency

### ECSS-E-TM-10-21A: MODELLING & SIMULATION ENG. PROCESS



### Model / Simulation Development





Satellite Missions of the European Space Agency

# ROLE OF THE EUROPEAN SPACE OPERATIONS CENTRE (ESOC)

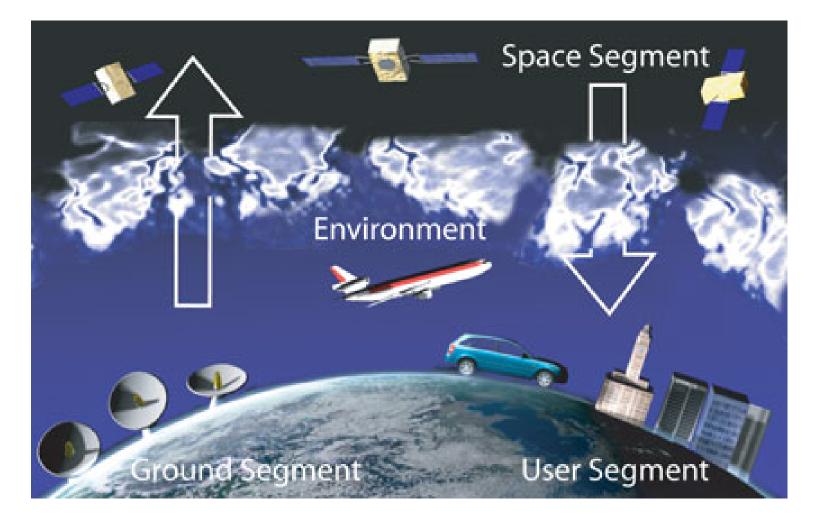
- ⇒ "Seconds after separation from the launcher [...] the spacecraft becomes the responsibility of the teams at ESOC."
  - MissionPlanning
  - MissionOperations
  - MissionDisposal





Satellite Missions of the European Space Agency

### **ELEMENTS INVOLVED IN A SATELLITE MISSION**





Satellite Missions of the European Space Agency

### INTERFACE BETWEEN ESOC AND A SPACECRAFT

- ESOC Monitor a Spacecraft via Telemetry
  - Telemetry is generated by each subsystems of the Spacecraft
  - Telemetry is emitted by the Spacecraft to send data back to Earth
  - Telemetry is received by a Ground Station Receiver
  - Telemetry is visualised using the <u>Satellite Control and Operation System</u> (SCOS)
- Secontrol a Spacecraft via **Telecommands** 
  - Telecommands are assembled by a Spacecraft Controller via SCOS
  - Telecommands are transmitted by a Ground Station Transmitter
  - Telecommands are received by the Spacecraft
  - ✤ Telecommands are (typically) processed by the On-Board Computer



Architecture of a S/C, and a Reference Architecture for Simulators

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#### Architecture of a Spacecraft, and a Reference Architecture for Simulators

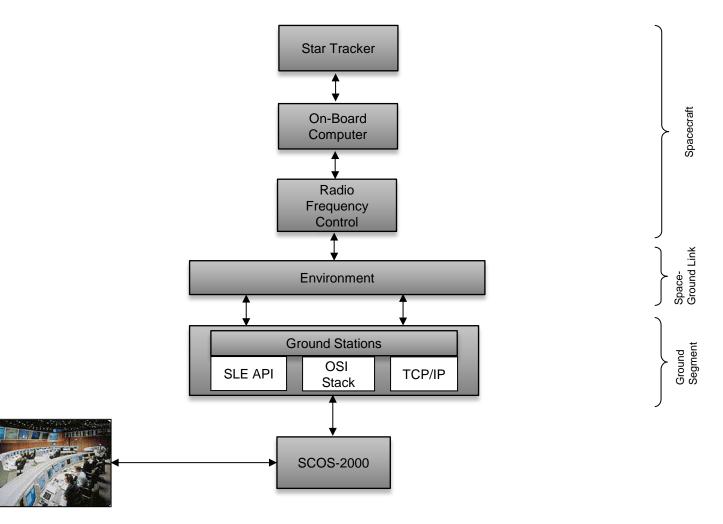
- High-Level Architecture of a Spacecraft
- Approach for a Reference Architecture to facilitate Model Re-Use
- ✤ Example of a specific instrument
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Architecture of a S/C, and a Reference Architecture for Simulators

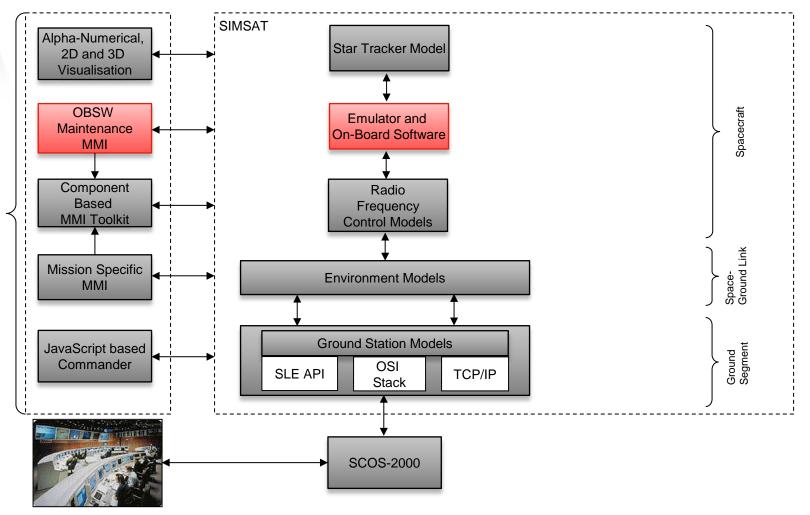
### DATA FLOW BETWEEN ESOC AND A STAR TRACKER





Architecture of a S/C, and a Reference Architecture for Simulators

### DATA FLOW BETWEEN ESOC AND A STAR TRACKER MODEL

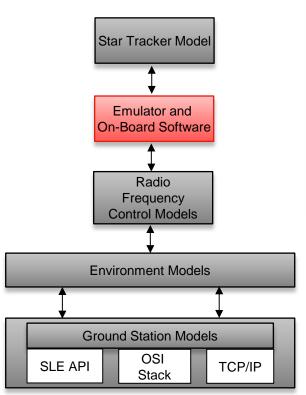




Architecture of a S/C, and a Reference Architecture for Simulators

### APPROACH FOR SPACECRAFT SIMULATION

- For all Spacecraft Subsystems, a <u>Ref</u>erence <u>Architecture</u> (**REFA**) has been established
  - Architecture defines common components and interfaces between them
  - Architecture makes use of common libraries
- The On-Board Software is used from the Mission
- The Emulator is generic (per Processor) and can be re-used across missions
- The Environment Models are implemented as a Library which can be configured per Mission
- Ground Station Models are independent of a specific S/C and can be re-used across missions





ARCHITECTURE & DEVELOPMENT PROCESS OF S/C SIMULATORS Architecture of a S/C, and a Reference Architecture for Simulators

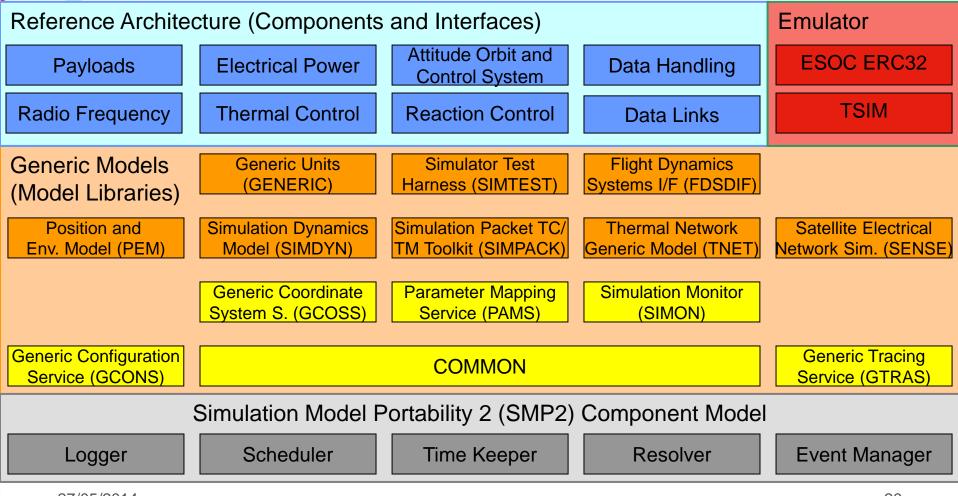
### THE SPACECRAFT SIMULATOR REFERENCE ARCHITECTURE

- ⇒ Defines a reference architecture for operational simulators for ESOC.
- Defines standard interfaces between common satellite subsystems' models
- ⇒ Used within ESOC's UML modelling framework (UMF)
- Strongly based on ESOC's <u>Gen</u>eric <u>Models</u> (GENM) Libraries
- Promotes consistency in design across the different mission simulators
   facilitates re-use of design and models.
- ⇒ No model implementation provided design only.
- ⇒ Can be extended to meet a particular mission simulator needs.
- ✤ Mission changes may feed back into the maintained REFA.



Architecture of a S/C, and a Reference Architecture for Simulators

# **REFERENCE ARCHITECTURE (REFA) AND GENERIC MODELS**





Architecture of a S/C, and a Reference Architecture for Simulators

### **REFA SUBSYSTEMS**

- The Reference Architecture covers the following subsystems
  - AOCS <u>Attitude and Orbit Control System</u>
  - DHS <u>Data Handling System</u>
  - ⇒ DL <u>D</u>ata Links

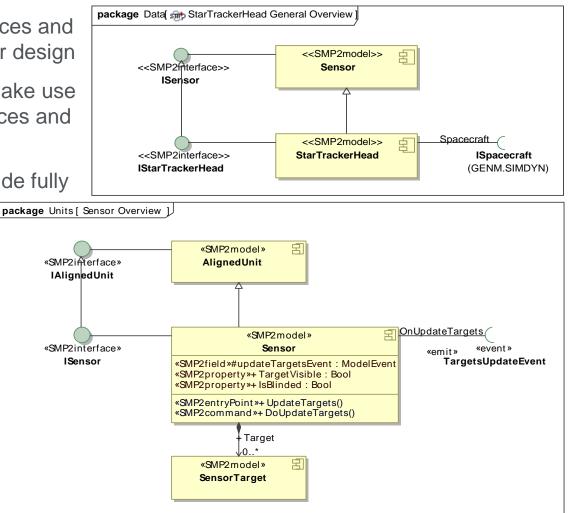
  - ⇒ RFCS <u>R</u>adio <u>F</u>requency <u>C</u>ontrol <u>S</u>ystem
  - ⇒ TCS <u>Thermal Control System</u>
  - ⇒ PL <u>Payloads</u> (only generic architecture)



Architecture of a S/C, and a Reference Architecture for Simulators

### **REFA EXAMPLE – THE STAR TRACKER HEAD ARCHITECTURE**

- REFA defines interfaces and "abstract" models for design
  - These models make use of GENM interfaces and model libraries
- GENM libraries provide fully tested code for common cases
- Missions need to "complete" their implementation by deriving from REFA



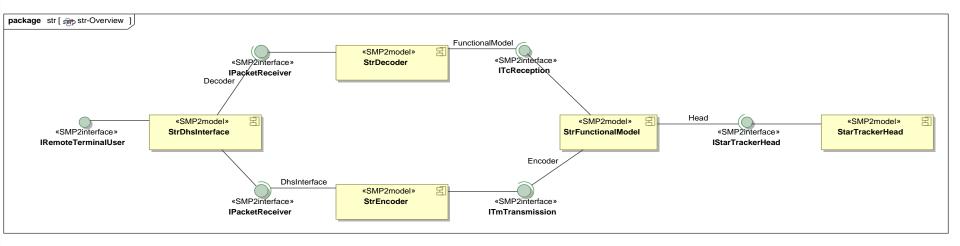


ARCHITECTURE & DEVELOPMENT PROCESS OF S/C SIMULATORS Architecture of a S/C, and a Reference Architecture for Simulators

### **REFA EXAMPLE – THE COMPLETE STAR TRACKER**

Scomplete Star Tracker (STR) design includes various other elements

- The STR communicates with the On-Board Computer via a Bus
- The STR decodes Telecommands and encodes Telemetry
- The STR implements a Functional Model (complex state machine)
- ⇒ The STR receives Measurements from the Star Tracker Head





**Development Process of Operational Spacecraft Simulators** 

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**Development Process of Operational Spacecraft Simulators** 

## **TECHNICAL CHALLENGES**

- Accurate Modelling of highly complex System
  - ⇒ High focus on formal testing and validation
- Demanding Requirements on Documentation
- ✤ Long-Term Maintenance until End of Mission
  - Typically requires migration to new platform/operating system
- Distributed Development Team
  - Fully integrated development environment across countries



**Development Process of Operational Spacecraft Simulators** 

## **RECENT TECHNOLOGIES**

- ⇒ Full Automation of Testing
  - Unit and Integration Testing is done via CppUnit / JUnit
  - System Testing is done via JavaScript procedures (Scripting Language)
  - ⇒ All Tests are executed every night ("nightly build and test approach")
- ⇒ Apply Model Driven Architecture (MDA) based development approach
  - Somplete system is modelled in <u>Universal Modelling Language</u> (UML)
  - ⇒ Source code is generated from UML Design
  - Documentation is generated from UML Design
- Strict Adherence to Open Standards
  - Solution Avoid dependency on a specific Platform, Operation System or Tool
  - ⇒ Use Static Code Analysis to detect platform specific code
  - Build and Test on various Operating Systems (LINUX, Windows)



**Development Process of Operational Spacecraft Simulators** 

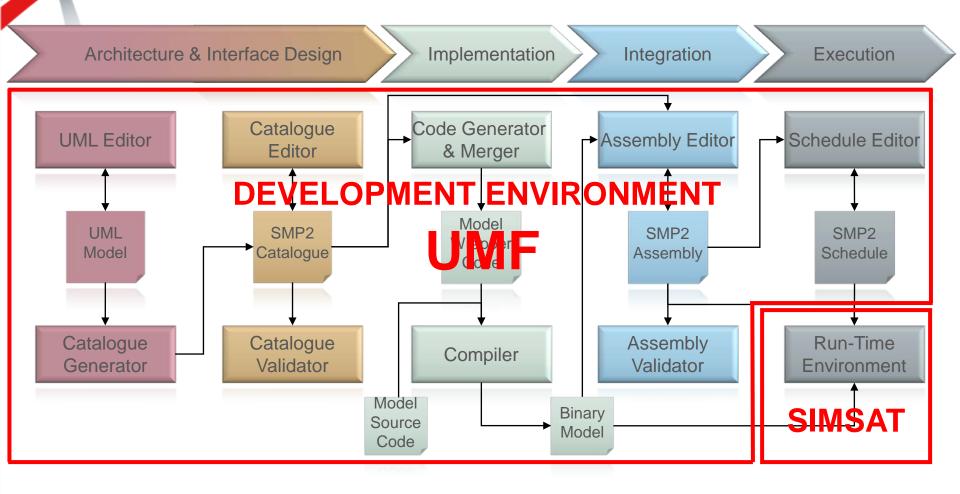
### MODEL DRIVEN ARCHITECTURE APPROACH FOR SIMULATORS

- ⇒ As a common simulation platform, a simulation standard has been defined
  - SMP2 is the Simulation Model Portability Standard by ESA
  - SMP is the Simulation Modelling Platform Standard by ECSS
- ✤ To support MDA, a Domain Specific Language (DSL) has been defined
  - The <u>Simulation Model Definition Language</u> (SMDL) is part of SMP2
  - ⇒ An Implementation of SMDL in a commercial UML tool is available
  - Tools to generate Documentation from SMDL have been developed
  - Solution Tools to generate C++ Source Code from SMDL have been developed
- ⇒ All Generic Models (GENM) have been migrated to SMDL and SMP2
- The Reference Architecture (REFA) has been defined using SMDL



**Development Process of Operational Spacecraft Simulators** 

### SMDL SIMULATION DEVELOPMENT LIFE-CYCLE AND TOOLS

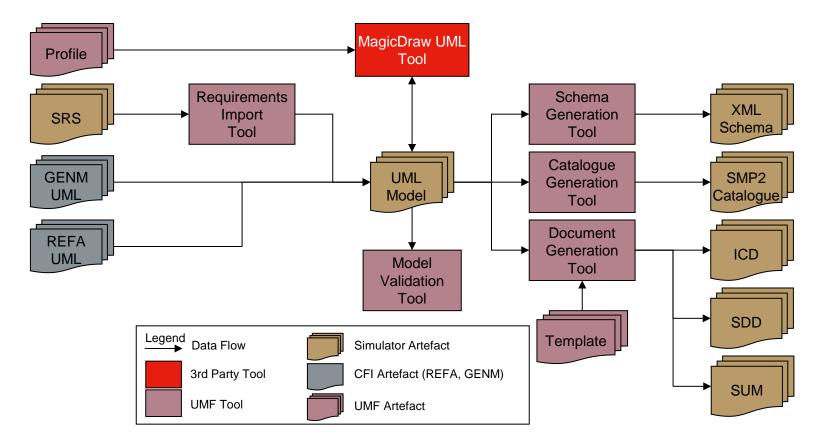




**Development Process of Operational Spacecraft Simulators** 

### SMDL MODEL DRIVEN DESIGN PROCESS

Usage of UMF Tools in the context of SMDL Model Driven Design (MDD)

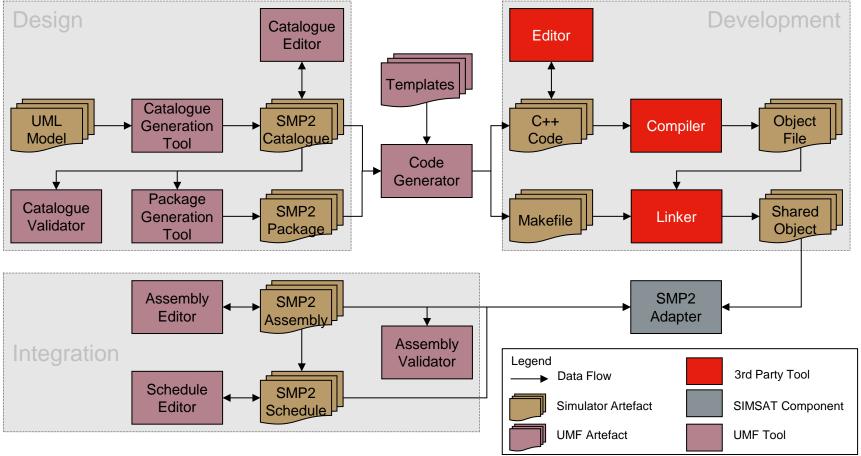




**Development Process of Operational Spacecraft Simulators** 

### SMDL MODEL DRIVEN SOFTWARE DEVELOPMENT USING SMDL

Usage of UMF Tools in the context of SMDL Model Driven Software Development



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**Development Process of Operational Spacecraft Simulators** 

### **PROCESS OBJECTIVES**

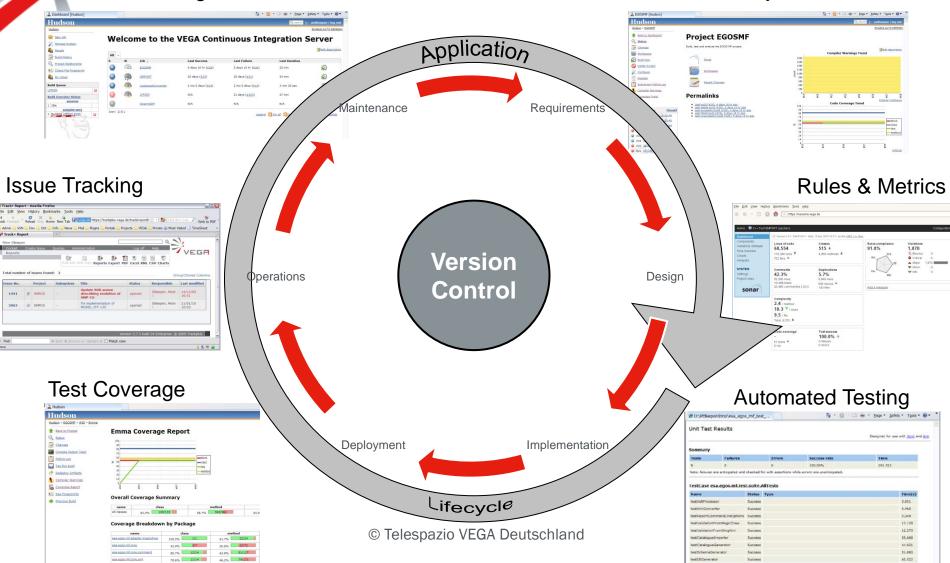
- Reduce Development Cost
- ⇒ Increase Number of Deliveries ("Incremental" or "Agile" approach)
- Compress Schedule
- Provide Transparency of current Status
- Subcontract at least 40% of the Development to a Qualified Partner (QPA)
- Share Hardware Resources between Missions



**Development Process of Operational Spacecraft Simulators** 

# APPLICATION LIFECYCLE MANAGEMENT (ALM)

**Project Dashboard** 





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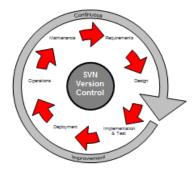
**ARCHITECTURE & DEVELOPMENT PROCESS OF S/C SIMULATORS** 

**Development Process of Operational Spacecraft Simulators** 

## <u>SYSTEM ENGINEERING AND SOFTWARE MANAGEMENT ENV.</u>

# SESOME

The Telespazio VEGA System Engineering and Software Management Environment



Application	Purpose	URL
🏟 Jenkins	Continuous Integration	https://sesome.telespazio-vega.de/jenkins https://sesome.telespazio-vega.de/hudson
sonarqube	Quality and Metrics	https://sesome.telespazio-vega.de/sonarqube https://sesome.telespazio-vega.de/sonar (old)
<b>∓∆</b>	Repository Browsing	https://svn.telespazio-vega.de/viewvc
M	Repository Access	Example for "sample" repository: https://svn.telespazio-vega.de/svn/sample
×	Issues and Tasks	https://jira.telespazio-vega.de/



**Development Process of Operational Spacecraft Simulators** 

### **Coverage Pipeline**





VALGRIND

#### **ARCHITECTURE & DEVELOPMENT PROCESS OF S/C SIMULATORS**

**Development Process of Operational Spacecraft Simulators** 

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s TPZV SNT EXMSIM EX	MSIM Coverage Pipeline Memory-Co	v-EXMSIM	#144	
Back to Project	Valgrind Res	ult (	Processes (	)verview)
<u>.</u>	Valgrina Res			
Status	Process	Parent	Errors	Bytes Leaked
Changes	esa.exmsim.assemblies.itest (19156)	16624	Leak (definitely lost) 3	Definitely Lost 17125408
Console Output			Uninitialized Condition 11	Definitely cost 17120400
dit Build Information	esa.exmsim.eps.itest (24779)	16624		
Delete Build	esa.exmsim.eps.itest (25109)	16624	Uninitialized Condition 27	
arameters	esa.exmsim.eps.itest (24258)	16624		
	esa.exmsim.eps.itest (24709)	16624	Uninitialized Condition 2	
ag this build	esa.exmsim.eps.itest (2476)	16624		
See Fingerprints	esa.exmsim.eps.itest (2631)	16624		
algrind Result	esa.exmsim.eps.itest (23146)	16624		
	esa.exmsim.eps.pcu.utest (23429)	16624		
ailure Cause Management	esa.exmsim.generic.utest (16651)	16624		
Downstream build view	esa.exmsim.gnc.css.itest (23530)	16624		
Build Artifacts As Maven Repository	esa.exmsim.gnc.css.utest (16740)	16624	Leak (definitely lost) 3	Definitely Lost 5252
wild Creat	esa.exmsim.gnc.imu.itest (21554)	16624		
Build Graph	esa.exmsim.gnc.imu.utest (16786)	16624	Leak (definitely lost) 2	Definitely Lost 3990



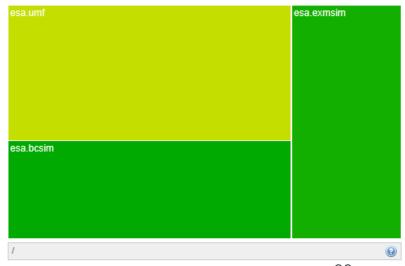
**SONARCUBE** 

#### **ARCHITECTURE & DEVELOPMENT PROCESS OF S/C SIMULATORS**

#### **Development Process of Operational Spacecraft Simulators**

Home

TOOLS	My favou	r <u>ites</u>					Pro	<u>jects</u>					
Dependencies	<u>A</u> Na	<u>me</u> ≜				Last Analysis		A	<u>Name</u> ≜	Version	LOCs	<u>RCI</u>	Last Analysis
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sonarqube							7	20	esa.exmsim	1.0.0-Sprint3	107,587 🛪	96.2%	07:06
	Projects i	<u>n error</u>					2		esa.umf	2.0.2-SNAPSHOT	159,465	61.6%	09 May 2014
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Manage dashboards



#### **Development Process of Operational Spacecraft Simulators**

DASHBOARD

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ter esaluciant					24			
Dashboard	Version 2.1.0-Sprint8 - 27 May 2014 04:12	me changes v			Manage dashboards			
Hotspots Issues Time Machine TOOLS Components	Lines of code <b>116,951</b> . <b>n</b> 369,671 lines . <b>n</b> 40,139 statements . <b>n</b> 1,546 files . <b>n</b>	Classes 517 . 4,078 functions .	Issues 78 . Technical Debt 0.0 days	<ul> <li>▲ Blocker</li> <li>▲ Critical</li> <li>▲ Major</li> <li>▼ Minor</li> <li>▼ Info</li> </ul>	0 3 🖓   24 💐 🗾 51 😭			
Issues Drilldown Design Libraries	Comments <b>54.5% ×</b>		① Alerts : Unit tests failures > 0.					
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sonarqube	Duplications 9.9% 36,421 lines . 800 blocks .		70.2% line coverage ¥ 65.1% branch coverage	4 failures 3 0 errors 352 tests 0 ms				
	365 files 🖣		Size: Lines of code Color:	Rules compliance 0.0%	100.0%			
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#### **Development Process of Operational Spacecraft Simulators**

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HOTSPOTS

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Dashboard	Version 2.1.0-Sprint8 - 27 May 2014 04:12 Time changes	•						Manage d	ashboards
Hotspots Issues Time Machine	Most Violated Rules Any severity 💌		More	Most Violated Resources					<u>More</u>
	Parenthesis in expressions	23		Definitions.h	1∆0	<b>a</b> 0	<b>▲</b> 7	₹2	♥0
TOOLS	Access to members data	16		Definitions.h	1€0	0 🕿	▲3	₹3	♥0
Components Issues Drilldown	Copy constructor	9		Definitions.h	1€0	0 🕿	▲3	₹2	❤0
Design	Default constructor	8		Definitions.h	1€0	0 🕿	▲3	₹2	♥0
Libraries	Destructor	6		Definitions.h	1€0	0 🕿	▲3	₹2	❤0
Clouds									
Compare	Hotspots by Unit tests duration		More	Hotspots by Uncovered lines					More
sonarqube				StrFunctionalModel.cpp			1,354		
	esa.bcsim.scenario.stest.02	0 ms		Dans.cpp			979		
	<u>StrNominalTest</u>	0 ms		Fpqa.cpp			354		
	PressureRegulatorTest	0 ms		SdramController.cpp			277		
	ArrayPowerRegulatorTest	0 ms		RfLinkHelper.cpp			269		
	MepsTest	0 ms					200	_	
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	StrFunctionalModel.cpp	462		TcTmModule.cpp			11.3		
	FunctionalModel.cpp	440		PowerSupplyUnit.cpp			11.3		
	Dans.cpp	341		SpaceWireController.cpp			10.2		
	Fpga.cpp	247		Dans.cpp			9.5		
07/05/00	Channes Value and	402		FunctionalModel.cpp			9.2	-	

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**TIME MACHINE** 

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Dashboard Hotspots	Version 2.1.0-Sprint8 - 27 I	May 2014 04:12 Tim	ne changes		¥				N	lanage dashboards
Issues Time Machine	Complexity: 11,09     Rules compliance	e: 99.9%	16 Mar 2014				17 Dec 2013	21 Feb 2014 2.1.0	27 May 2014 2.1.0-Sprint8	
Time Haenine	Coverage: 69.4%					Issues	0	140	78	
TOOLS						Blocker issues	0	0	0	
Components Issues Drilldown						Critical issues	0	7	3	
Design		~				Major issues	0	4	24	/
Libraries	03/2014	 04/2014		05/2014		Minor issues	0	129	51	
Clouds						Weighted issues	0	176	138	
Compare		17 Dec 2013 2	21 Feb 2014 2.1.0	27 May 2014 2.1.0-Sprint8						
	Lines of code	106,065	108,960	116,951	/		17 Dec 2013	21 Feb 2014 2.1.0	27 May 2014 2.1.0-Sprint8	
	Lines	340,007	346,182	369,671		Complexity	10,431	10,869	11,459	/
	Statements	36,162	37,608	40,139	/	Complexity /function	2.7	2.8	2.8	
	Files	1,514	1,529	1,546	/	Complexity /class	20.7	21.3	22.1	
	Classes	504	510	517	/	Complexity /file	6.9	7.1	7.4	
	Functions	3,796	3,907	4,078	/					
	Accessors						17 Dec 2013	21 Feb 2014 2.1.0	27 May 2014 2.1.0-Sprint8	
		17 Dec 2013	3 21 Feb 2014	27 May 2014		Coverage		70.8%	68.9%	
			2.1.0	2.1.0-Sprint8		Line coverage		73.0%	70.2%	
	Comments (%)	54.3%	54.0%	54.5%		Branch coverage		64.8%	65.1%	
27/05/20/	Comment lines	126.069	9 127.906	140.249	/	Linit kanta auraana (0)	<b>`</b>	00.00/	00.00/	20

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#### **Development Process of Operational Spacecraft Simulators**

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**COMPONENTS** 

						. 201
Dashboard		Name	Rules compliance	Coverage	Build time	Links
Hotspots	0 🚖	esa.bcsim	99.9%	68.9% <del>¥</del>	04:12	
Issues Time Machine						
Time Machine		Name	Rules compliance	Coverage v	Build time	Links
TOOLS	合 🗣	esa.bcsim.aocs.fss	100.0%	92.5%	04:12	
Components	倉 🔍	asa.bcsim.assemblies	100.0%	85.5%	04:12	
Issues Drilldown Design	會 Q	esa.bcsim.ttc	99.8%	83.1%	04:12	
Libraries	會 🧣	esa.bcsim.eps.bat	100.0%	82.5%	04:12	
Clouds	슬 🔍	esa.bcsim.aocs.rwl	99.9%	78.8%	04:12	
Compare	🚖 🔍	esa.bcsim.eps.sa	99.8%	78.1%	04:12	
sonarqube	술 🔍	esa.bcsim.cps	100.0%	78.0%	04:12	
	會 🔍	esa.bcsim.aocs.imu	99.8%	76.9%	04:12	
	合 🔍	esa.bcsim.dms.tctm	100.0%	75.5%	04:12	
	會 🔍	esa.bcsim.mechanisms.magboom	100.0%	74.6%	04:12	
	盒 🔍	esa.bcsim.eps.pcdu	99.8%	74.6%	04:12	
	🚖 🔍	esa.bcsim.dms.ssmm	100.0%	74.0%	04:12	
	술 💊	esa.bcsim.tcs	99.9%	73.7%	04:12	
	🚖 🔍	asa.bcsim.dms.rm	100.0%	73.1%	04:12	
	술 9	esa.bcsim.generic	100.0%	69.3%	04:12	
	🚖 Q	esa.bcsim.dms.common	100.0%	69.2%	04:12	
	<u> _</u> _	🕞 esa.bcsim.dms.riu	100.0%	69.1%	04:12	
	🚖 🔍	asa.bcsim.datalinks	100.0%	67.7%	04:12	
27/05/201	1 /				40	



#### **Development Process of Operational Spacecraft Simulators**



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#### **ISSUES DRILLDOWN**

Dashboard	Profile Sonar way with Logiscope	Time changes	¥			
Hotspots	Severity	Rule				
Issues	1 Blocker 0	All variables mus	t be initialized before being used		2	2
Time Machine	🕿 <u>Critical</u> 3	Pointer initializati	on			E
TOOLS	🔺 <u>Major</u> 24 📰	Access to memb	ers data		16	6
Components	▼ Minor 51	Destructor			(	5
Issues Drilldown	♥ <u>Info</u> 0	Prefer C++-style	<u>casts</u>			1
Design		<ul> <li>Try blocks in des</li> </ul>	tructors			·   -
Libraries Clouds	🔍 🕞 <u>esa.bcsim.eps.pcdu</u>	16 🔺	🔍 🚞 esa/bcsim/eps/pcdu/mpo	11 🔺	Definitions.h	9 🔺
Compare	🔍 🕞 esa.bcsim.mechanism	<u>ns.sada</u> 15 <sub>≣</sub>	🔍 🚞 esa/bcsim/mechanisms/sada/mpo	10 ≡	Definitions.h	6
	🔍 🕞 esa.bcsim.mechanism	ns.apme 12	🔍 🗖 esa/bcsim/meps	8	Definitions.h	5
sonarqube	) 🕞 esa.bcsim.ttc	8	🔍 🚞 esa/bcsim/ttc	8	🕑 🗎 Definitions.h	5
	🔍 🖬 esa.bcsim.meps	8	🔍 🚞 esa/bcsim/mechanisms/apme/hgama	6	🕑 🗎 Definitions.h	5
	🔍 🕞 esa.bcsim.eps.sa	7 👻	🔍 🚞 esa/bcsim/eps/pcdu/mtm	5 👻	🖻 🗎 Definitions.h	5 🚽
						Bulk Change

Bulk Change

Se	e. <u>Status</u>	Description	Component	Assignee	Action plan	Updated
•	Open	<pre>writeValue = static_cast&lt;::Smp::UInt16 &gt;(( buffer[itRegister] ) &amp; 0xFFFF)</pre>	esa.bcsim esa/bcsim/dms/rm/MemoryLogicBase.cpp			26 Apr 2014
•	Open	( ( breakwireExecuted == false ) && ( enabled == true ) && ( breakwireEvent.ge	esa.bcsim esa/bcsim/eps/pcdu/mpo/Dplm.cpp			04:12
•	Open	((i < ( static_cast<::Smp::Int64 >(MPO_FPGA_EEPROM_BYTE_SIZE) / 2 ) ) && (	esa.bcsim esa/bcsim/eps/pcdu/mpo/Fpga.cpp			04:12
•	Open	<pre>block.get_Data()[0 + k * 2] = static_cast&lt;::Smp::Int8 &gt;(buffer[k] &amp; 0xFF)</pre>	esa.bcsim esa/bcsim/eps/pcdu/mpo/Fpga.cpp			03 Mar 2014
	Open	DpImSelection	esa.bcsim			03 Mar 2014
7/05/2014		© Telespazio VEGA Deutschlar	nd		2	1



**SUBVERSION** 

#### **ARCHITECTURE & DEVELOPMENT PROCESS OF S/C SIMULATORS**

#### **Development Process of Operational Spacecraft Simulators**

SubversionEdge	Roots Changes	set Chan	ge Log Di	rectory Logged in as: pfritzen	Help 🗸
[bcsim] / trunk / Src					
trunk/Src					► r370
♦ File	≑ Rev.	<b>≑ Age</b>	Author		
<b>€</b> /					
💐 esa.bcsim/	3673	6 weeks	pellsiepen	sim#2033 simulus5#119: Updated solution Makefile and associated template such th	
💐 esa.bcsim.aocs/	3617	2 months	dsegneri	Merged SIMULUS_5.4 branch into trunk	
🐧 esa.bcsim.aocs.fss/	3617	2 months	dsegneri	Merged SIMULUS_5.4 branch into trunk	
🐧 esa.bcsim.aocs.imu/	3759	7 days	fmatera	IMU-FCE integration improved	
🐧 esa.bcsim.aocs.rwl/	3722	3 weeks	dsegneri	Change needed to be compatible with two REFA varsions	
🐧 esa.bcsim.aocs.str/	3693	6 weeks	fmatera	Initialization of STR power on state updated in StrFunctionalModel	
🕽 esa.bcsim.assemblies/	<u>3731</u>	2 weeks	clourenco	BepiSIM#306: Added a switchWhileOff bool field which, when true, allows the TSW $\ldots$	
🕽 esa.bcsim.configurations/	37 View	directory revision	on log atera	IMU-FCE integration improved	
🕽 esa.bcsim.cps/	3713	4 weeks	clourenco	Moved Thruster's lastUpdateTime and firingUpdateEventId fields into the model. A	
🕽 esa.bcsim.datalinks/	3720	3 weeks	ezanatta	Corrected non compliances to coding standard rules from Format Checker	
🕽 esa.bcsim.dms/	3720	3 weeks	ezanatta	Corrected non compliances to coding standard rules from Format Checker	
🕽 esa.bcsim.dms.common/	3738	2 weeks	dsegneri	Provided fix for SPR BepiSIM#275. Design needs to be updated and test implemente	
🐧 esa.bcsim.dms.fce/	3720	3 weeks	ezanatta	Corrected non compliances to coding standard rules from Format Checker	
🕽 esa.bcsim.dms.obc/	3720	3 weeks	ezanatta	Corrected non compliances to coding standard rules from Format Checker	
🕽 esa.bcsim.dms.pm/	3721	3 weeks	mirvine	Add UART2 register used by OBSW during boot (but UART2 not used during run of ap	
27/05/2014			© Teles	bazio VEGA Deutschland	42



References

## REFERENCES

- Some images have been taken from <u>www.esa.int</u> and are Copyright by ESA
- Some information has been taken from <a href="http://www.wikipedia.org">www.wikipedia.org</a>



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