

# SEAMLESS USER EXPERIENCE IN DRIVING SIMULATION STUDIES



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# ISSUES

Some users do not consider driving simulators as a realistic vehicle [1]

Perception from outside the simulation environment reduces the presence [2]



# PRESENCE

Sense of being in a particular place [3]

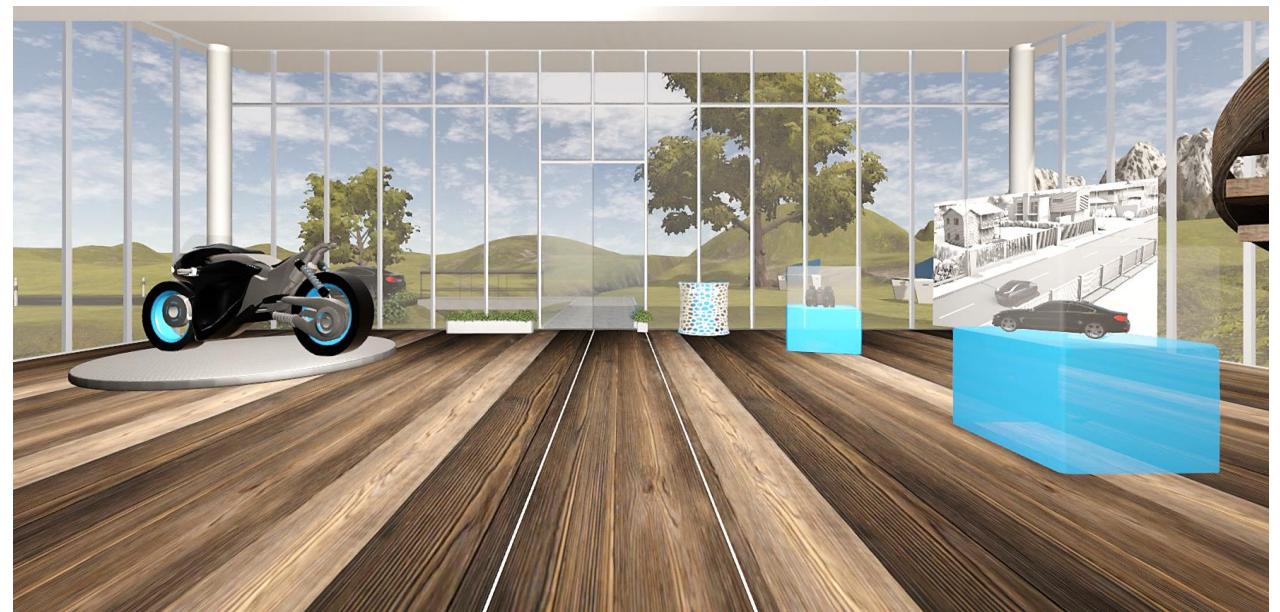
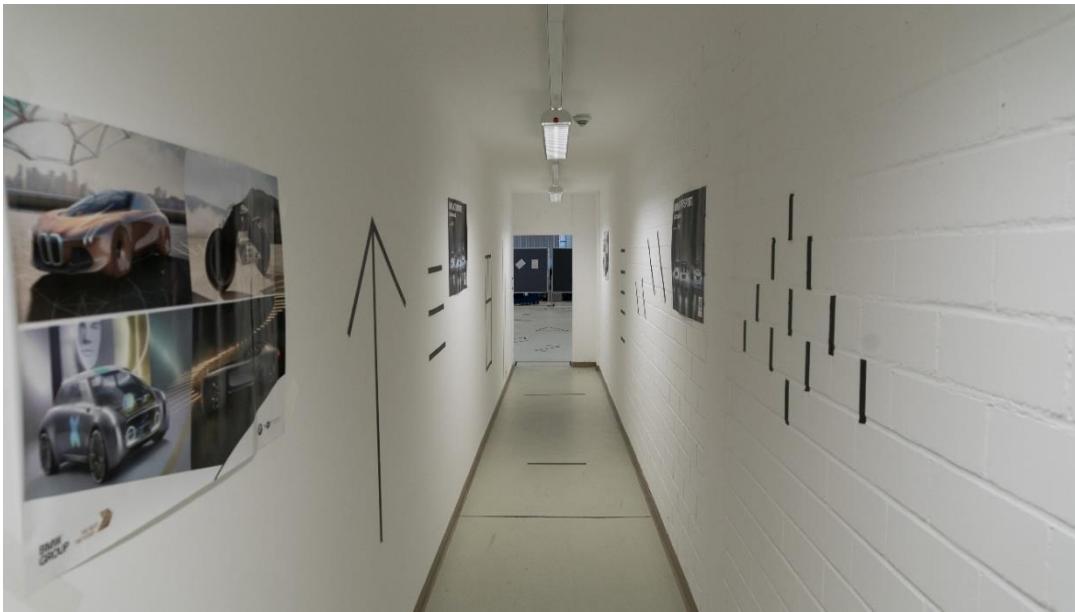
**Presence** = Place Illusion (**PI**) + Plausibility Illusion (**Psi**) [4]

**PI** - illusion of location

**Psi** - illusion that what is happening is really happening

# CONCEPT

Guiding participants to the simulator through the virtual transition environment displayed in VR HMD

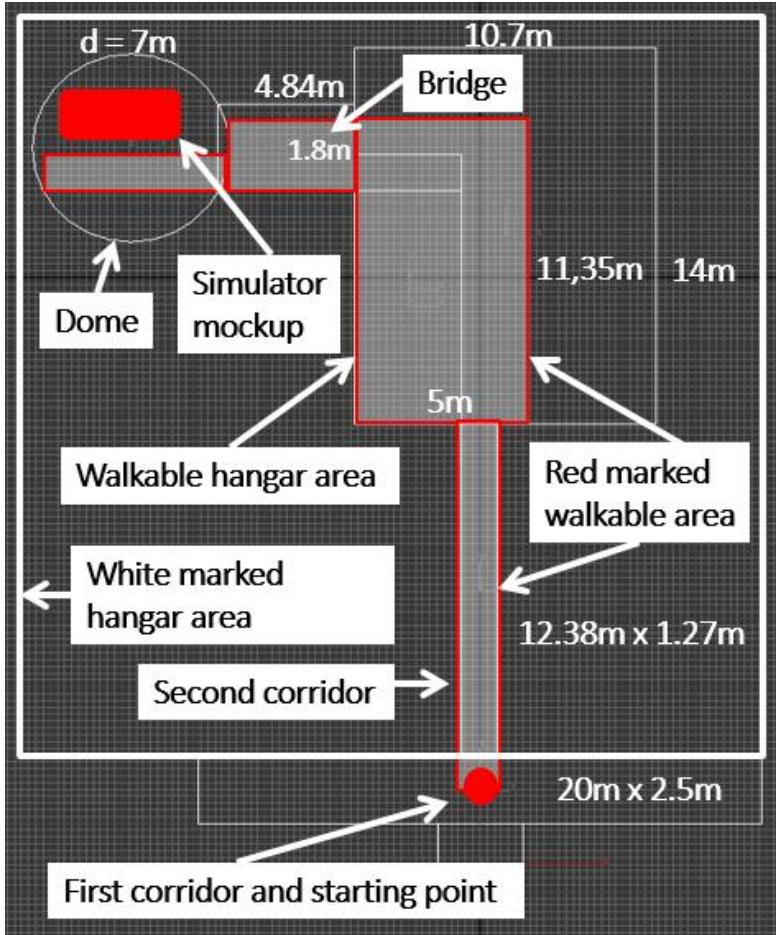


## HYPOTHESIS

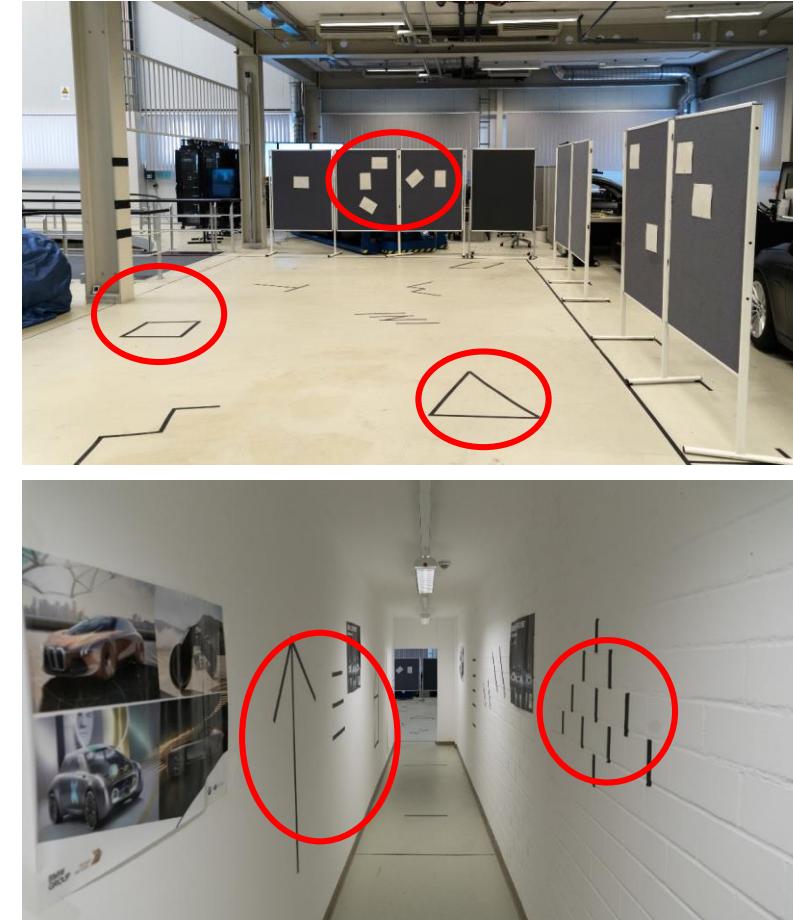
The participants exposed to the virtual transition environment have a stronger sense of presence during the driving simulation than the group that enters the simulator through the real hallways.

# CHALLENGES

## Real rooms plan



## Inside-out tracking stabilization



# TECHNICAL SOLUTION

## Dell Visor Windows Mixed Reality HMD

- 90 FPS
- Inside-Out Tracking
- 1440x1440 liquid crystal displays
- 105° horizontal FOV



## MSI Backpack PC VR One 7RE-083

- Intel® Core™ i7-7820HK, 4x 2.90 GHz
- Nvidia GeForce GTX1070
- 16 GB RAM, 512 GB SSD



# TECHNICAL SOLUTION

## Dynamic Driving Simulator

- 6 DOF hexapod-based motion system
- 240° projection
- Vehicle mock-up placed in the dome



# EXPERIMENT DESIGN

Between-subjects design: comparison VR group vs. Not VR group

Subjective measurements:

- Self-report questionnaires (*PED, SSQ, IPQ, SUS*)
- Immediate feedback assessment (*presence question, criticality question*)

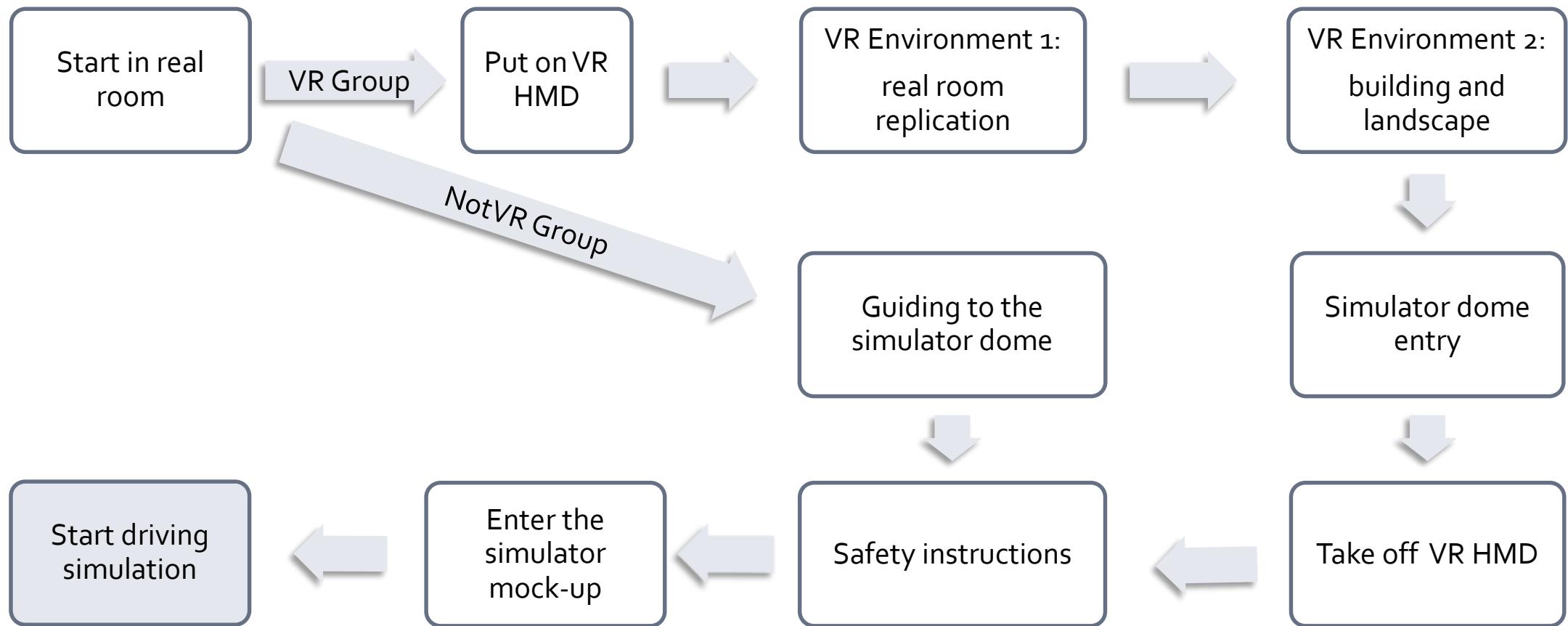
Explorative measurements:

- Behaviour observation (*call response*)
- Creative tasks (*only VR group*)

Objective measurements:

- Driving behaviour (*velocity, brake, lane offset*)
- Physiological data (*heart rate, skin conductance*)

# EXPERIMENT PROCEDURE



Master Thesis Project

# „Seamless User Experience in Driving Simulation Studies.”

by Victoria Ivleva

Supervisors:

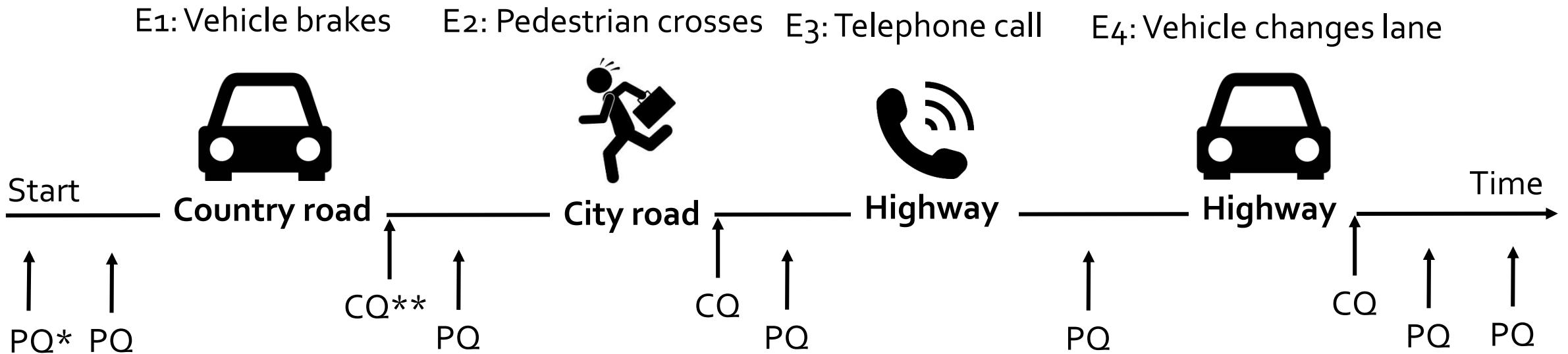
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Sergej Holzmann, BMW AG

Cooperation BMW AG Driving Simulation Center with University of Bremen Digital Media department

12.2017-06.2018 München

# DRIVING SIMULATION SCENARIO

4 critical events, 3 road types, 2 questions

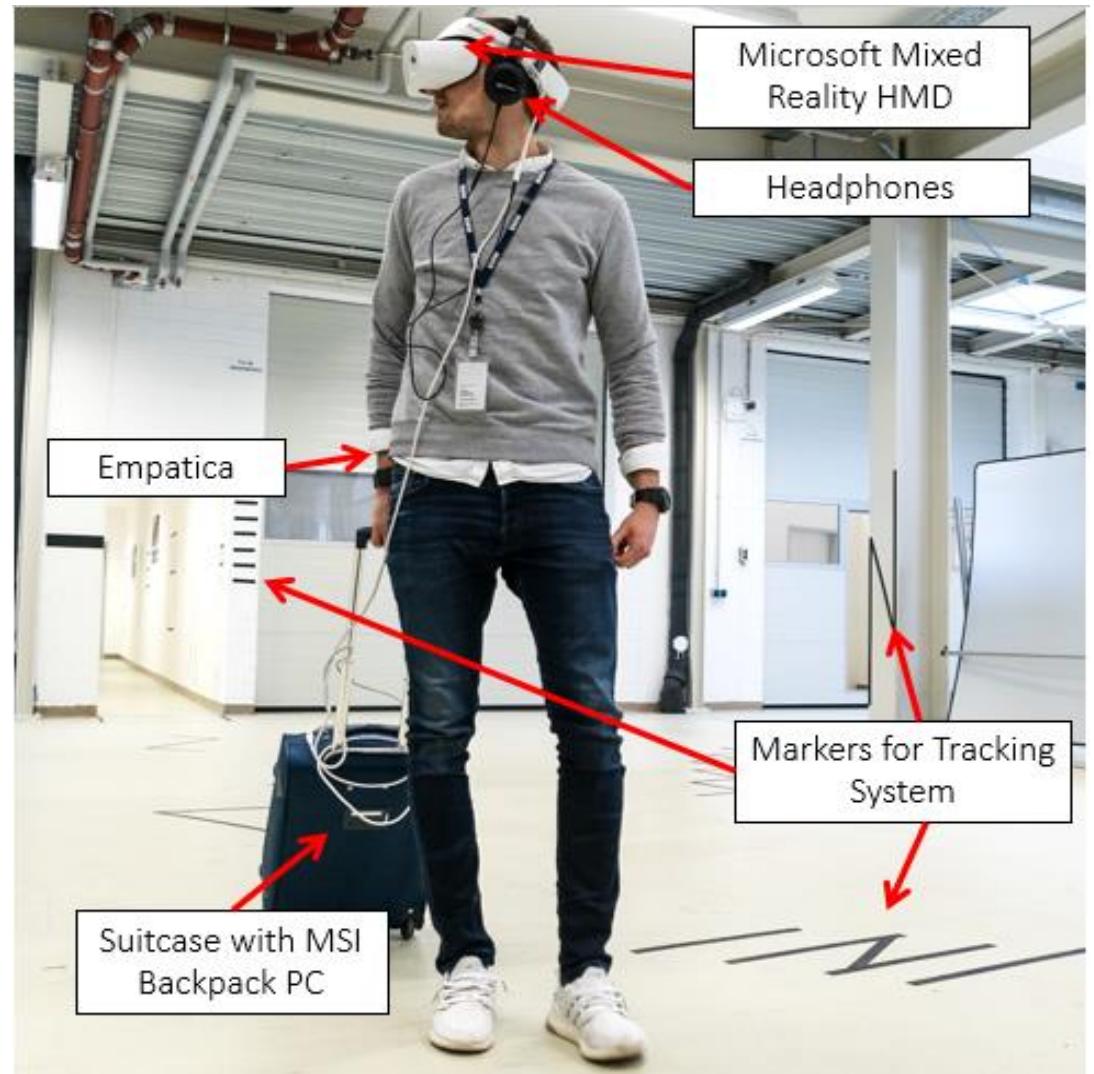


\*Presence question: „Please rate your presence on a scale of 1 to 10“

\*\*Criticality question: „How critical was the situation, please rate from 1 to 3“

# USER STUDY PARTICIPANTS

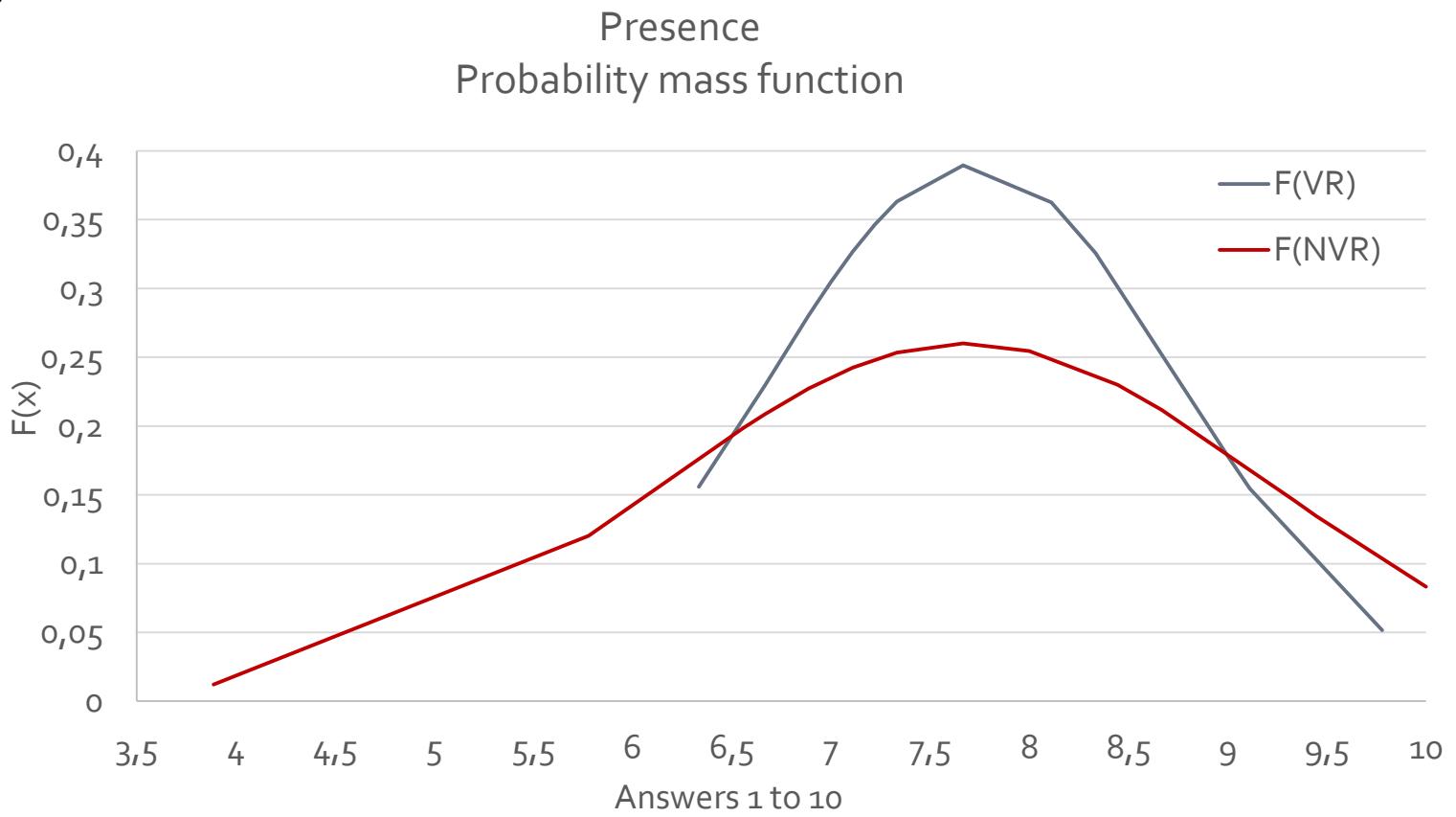
- 41 participants
- 19 participants in each group
- 3 participants aborted participation
- 68% man, 32% woman, 23-60 y.o.
- 80% have VR experience
- 54% have driving simulation experience
- 12 years average driving experience
- 49% engineers, 20% IT specialists



# RESULTS: IMMEDIATE FEEDBACK ASSESSMENT

## Sense of Presence while driving

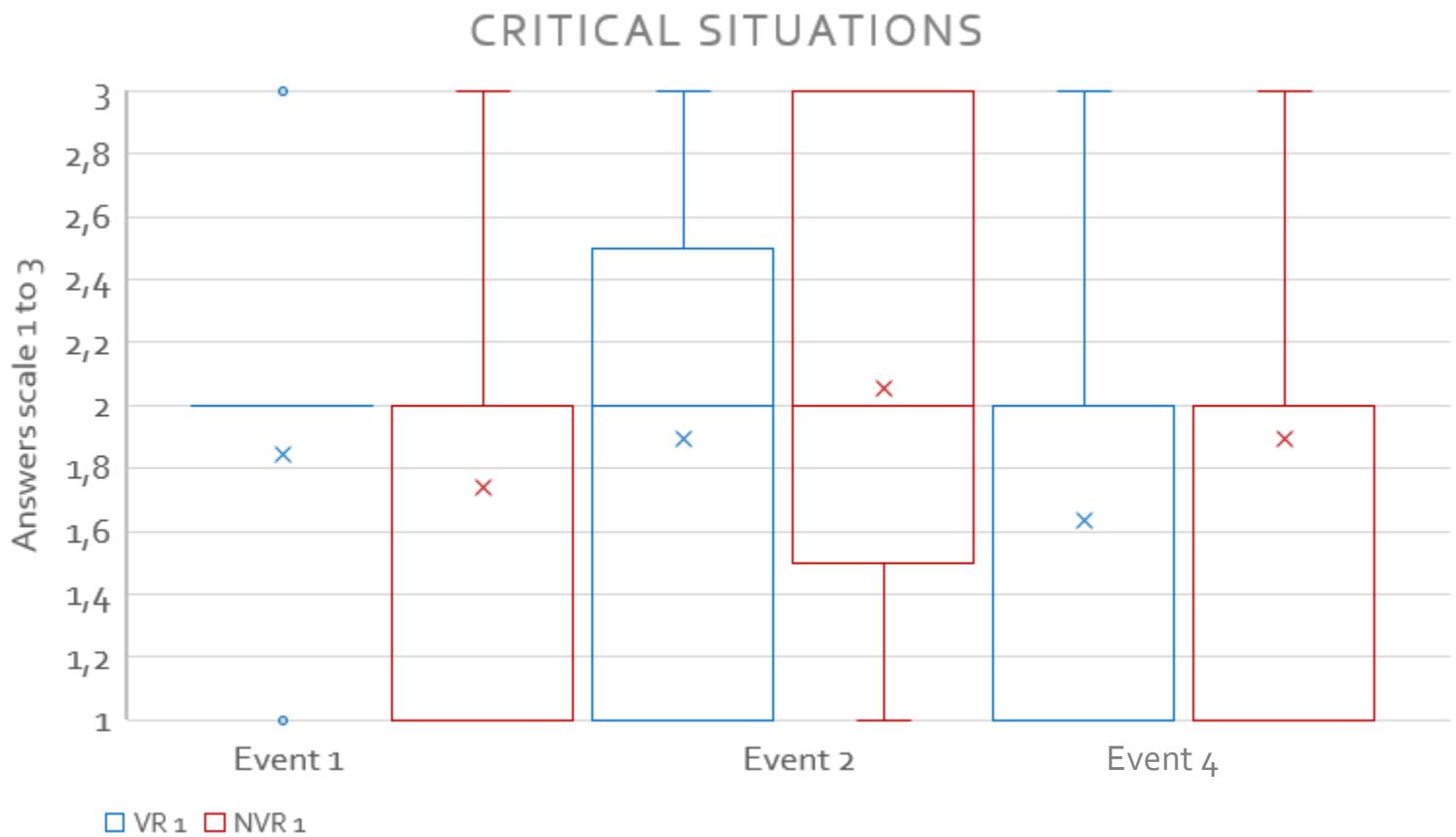
- Single-question
- Repeated 9 times
- Answer scale 1 to 10



# RESULTS: IMMEDIATE FEEDBACK ASSESSMENT

## Critical situations while driving

- 3 events
- Single-question
- Answer scale 1 to 3



# RESULTS: DRIVING BEHAVIOUR

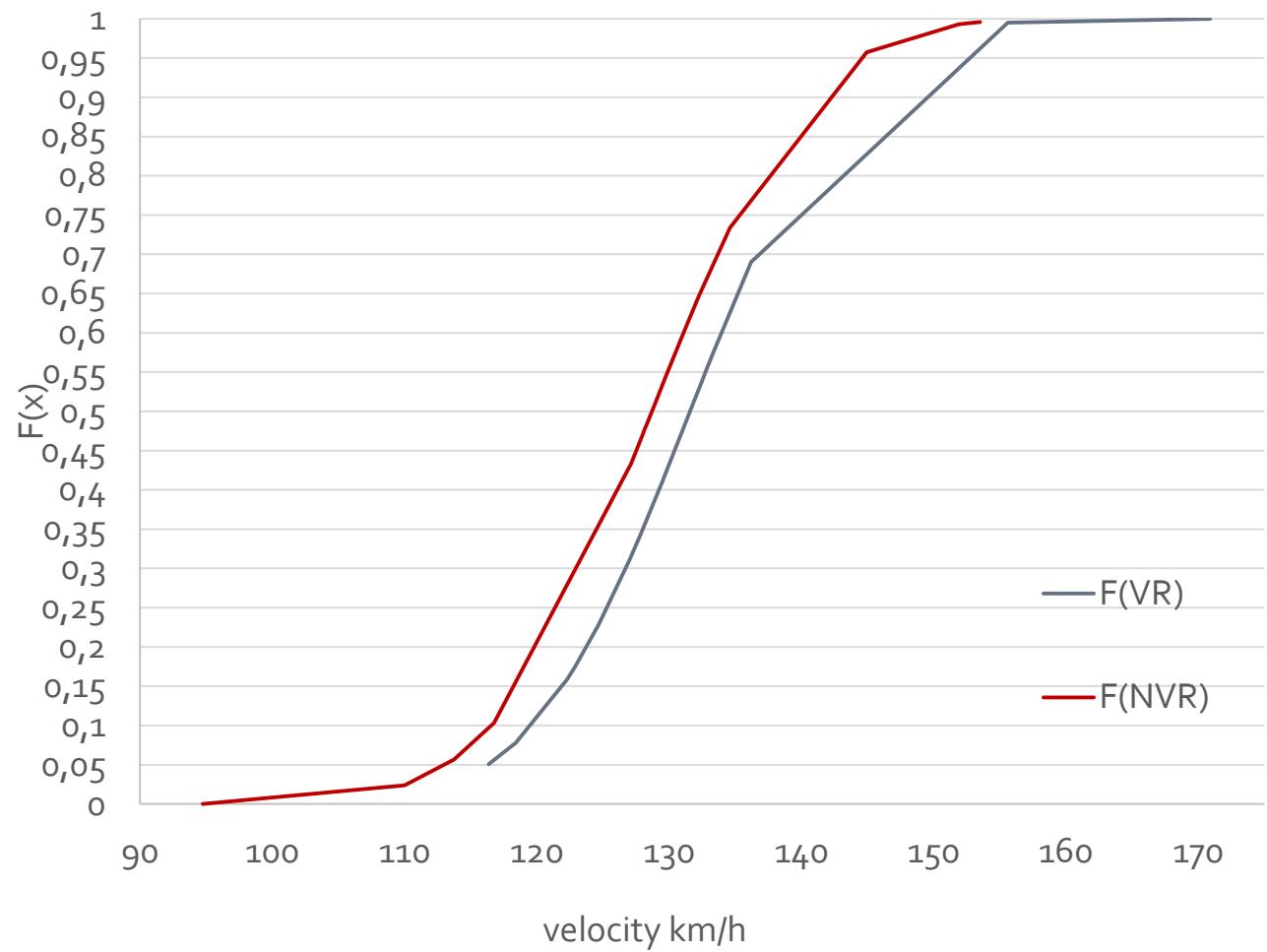
## Driving velocity

- Country road – no significant difference
- City road- no significant difference
- Highway VR > NVR (3 km/h)

## Self-estimation velocity

- Real world driving velocity > simulator
- Especially on the highway (max. 27 km/h)

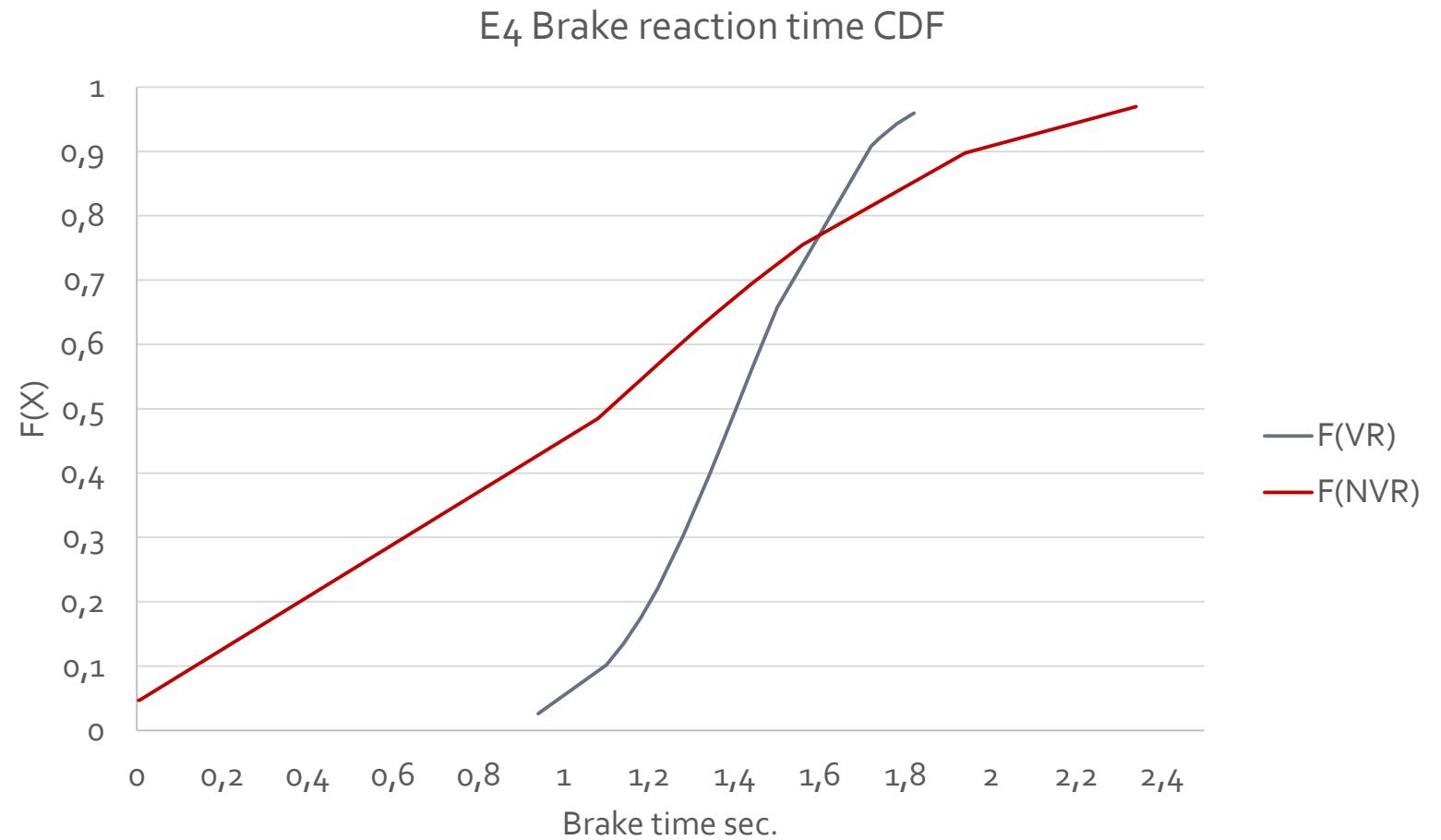
Highway velocity CDF



# RESULTS: DRIVING BEHAVIOUR

Brake reaction time  $br = tb - ts$

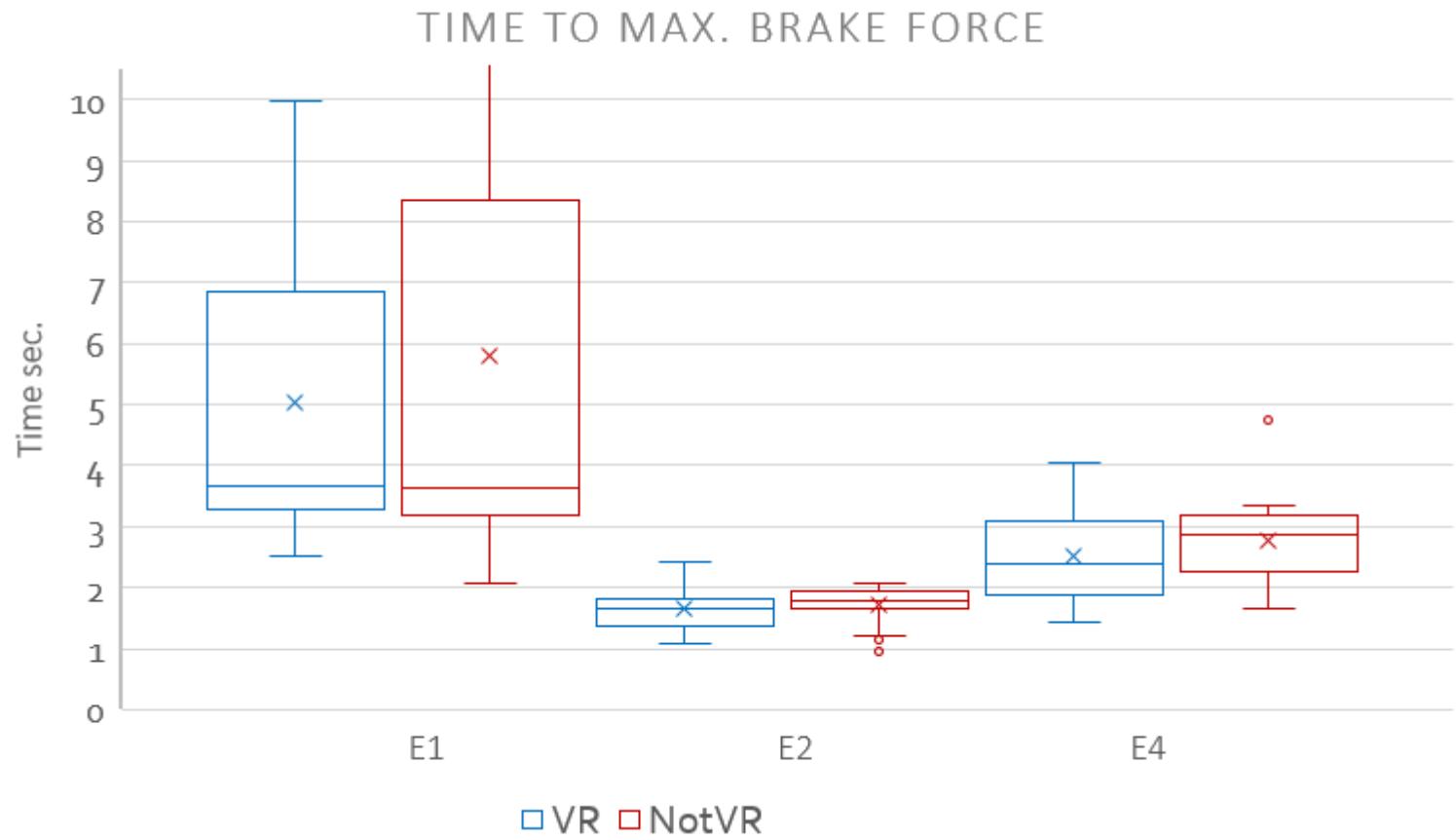
- E<sub>1</sub> VR > NotVR 0.5 sec.
- E<sub>2</sub> VR < NotVR 0.4 sec.
- E<sub>4</sub> VR > NotVR 0.9 sec.



# RESULTS: DRIVING BEHAVIOUR

## Brake reaction time to max force

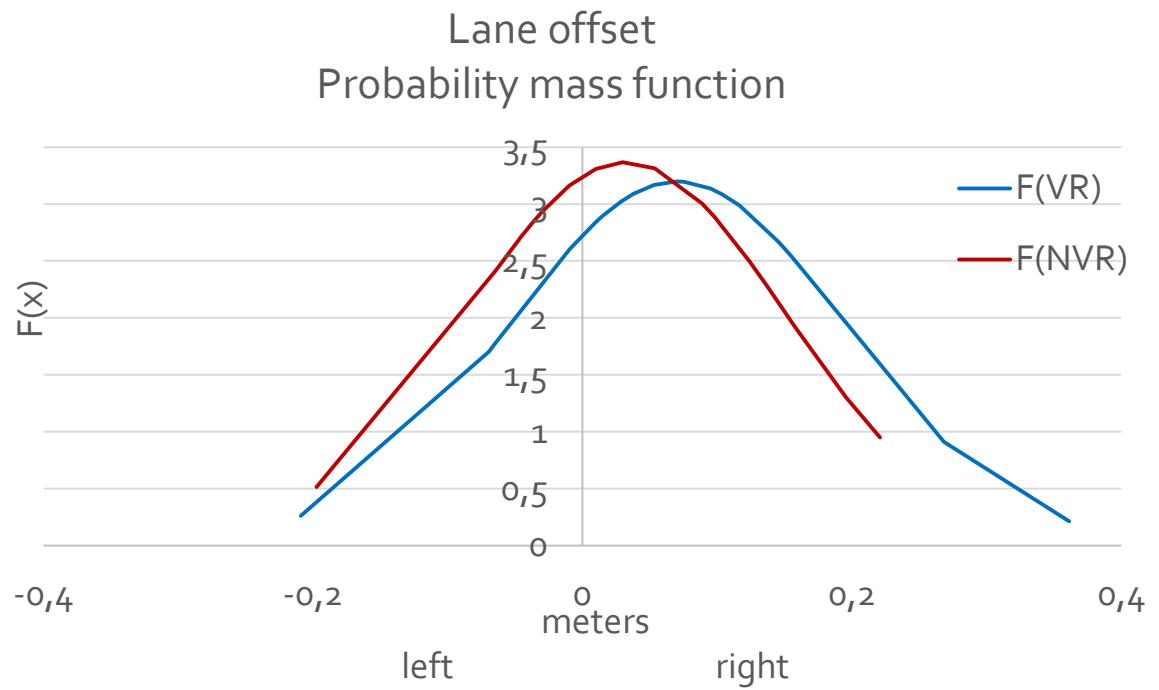
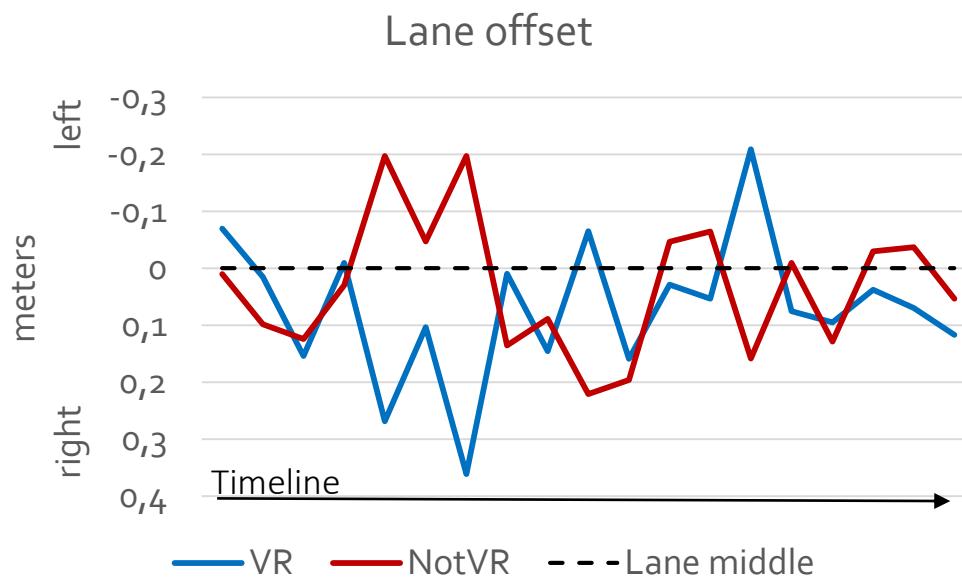
- E<sub>1</sub> VR < NotVR
- E<sub>2</sub> VR < NotVR
- E<sub>4</sub> VR < NotVR



# RESULTS: DRIVING BEHAVIOUR

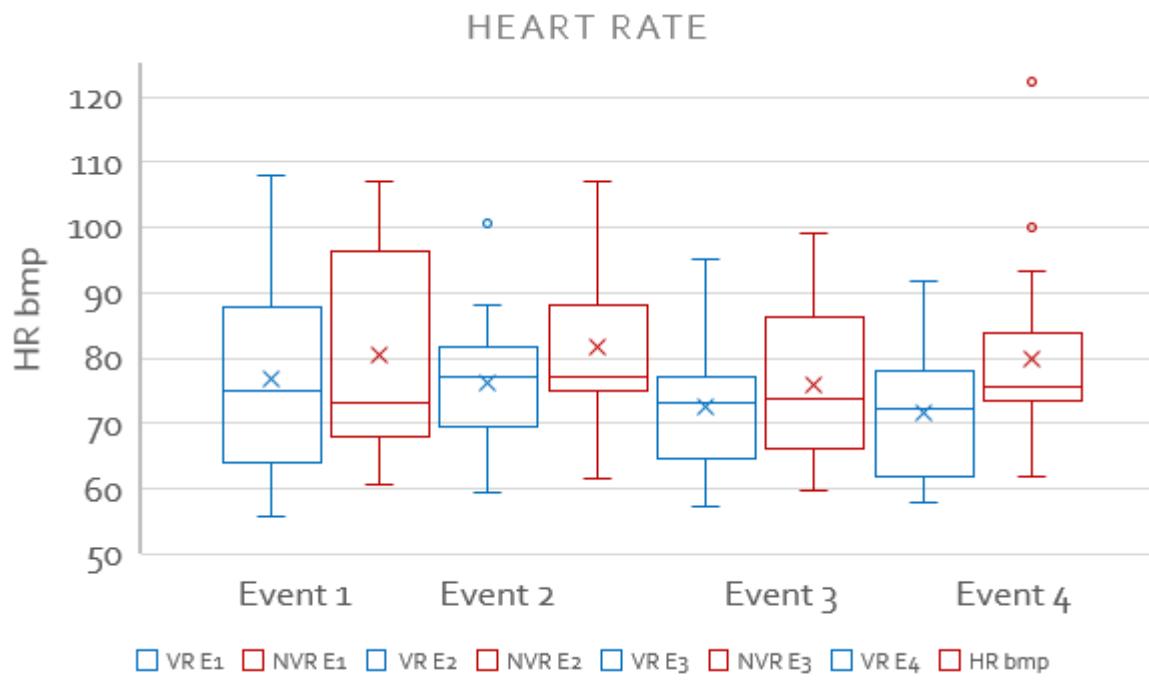
## Lane offset

$$m = \frac{r + l}{2} - r$$

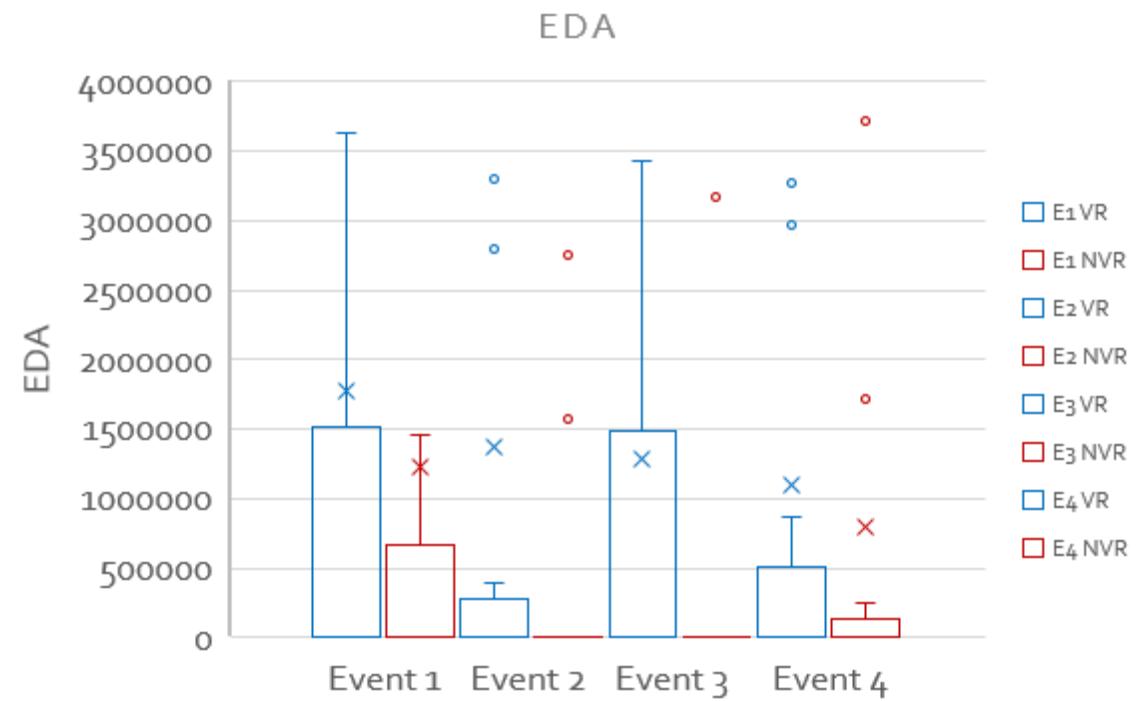


# RESULTS: PHYSIOLOGICAL DATA

Heart rate (*beats per minute*)

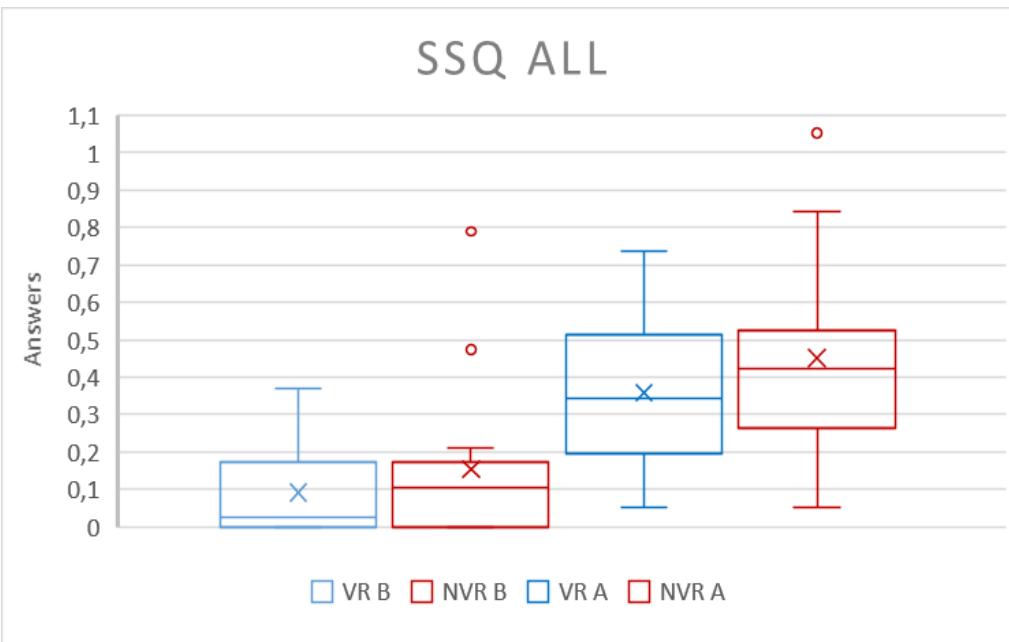


Skin conductance (*micro-Siemens*  $\mu$ S)



# RESULTS: SUBJECTIVE DATA

## Motion Sickness Questionnaire



## Igroup Presence Questionnaire

- Spatial Presence: no significant difference
- Involvement: no significant difference
- Realness perception: VR > NotVR

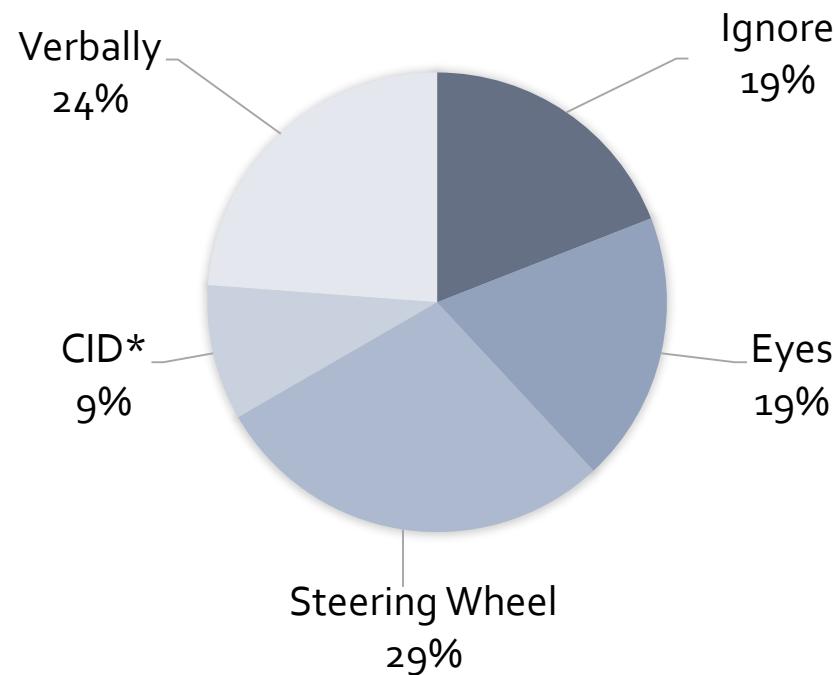
## Slater-Usoh-Steed presence questionnaire

- Overall score of high responses (*max 49*)
- VR 30 > NotVR 25

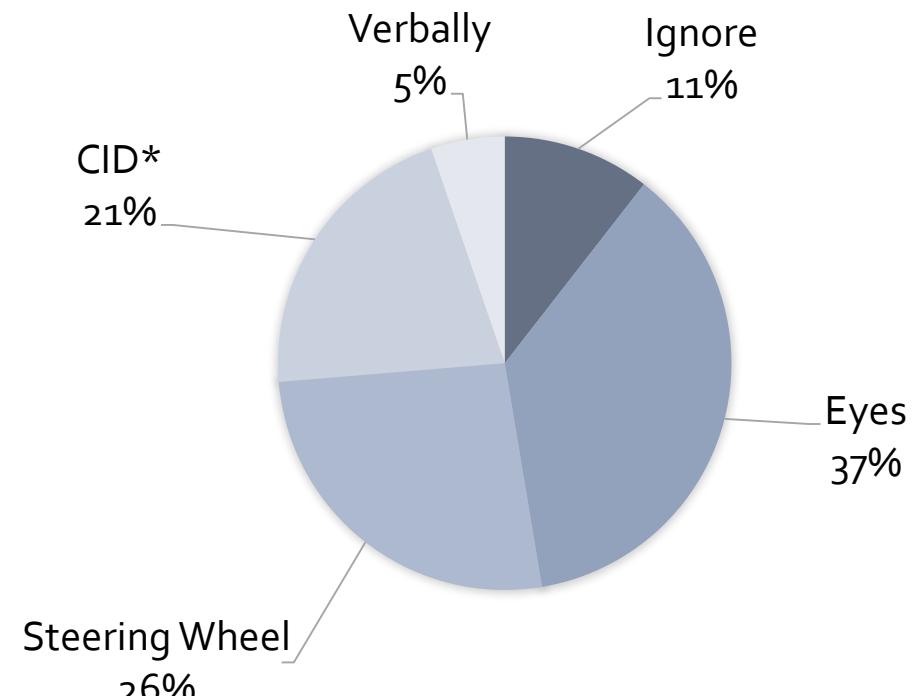
# EXPLORATIVE RESULTS: BEHAVIOUR OBSERVATION

## Phone call response

- VR Group



- NotVR Group



\*Central Information Display

# EXPLORATIVE RESULTS: CREATIVE TASK



- Realistisch - realistic
- Zukunft - future
- Einladend - inviting
- Schön - beautiful
- Sauber - clean
- Angenehm - enjoyable
- Freundlich - friendly
- Künstlich - synthetic
- Einsam - lonely
- Leer - empty
- Sauber - clean

# CONCLUSION: FINDINGS

## Driving behaviour and immediate self-assessment feedback

- No significant difference between VR and Not VR groups

## Physiological data

- Not significantly different between the groups, NotVR group had higher heart rate

## Questionnaires IPQ, SUS

- VR group reported significantly higher realness perception and sense of presence
- No significant difference in spatial perception and involvement (attention)

## Explorative data

- VR Transition had an impact on users' perception and behaviour

## FUTURE DIRECTIONS

Take off the VR HMD inside of the simulator mock-up

Increase the time in the VR

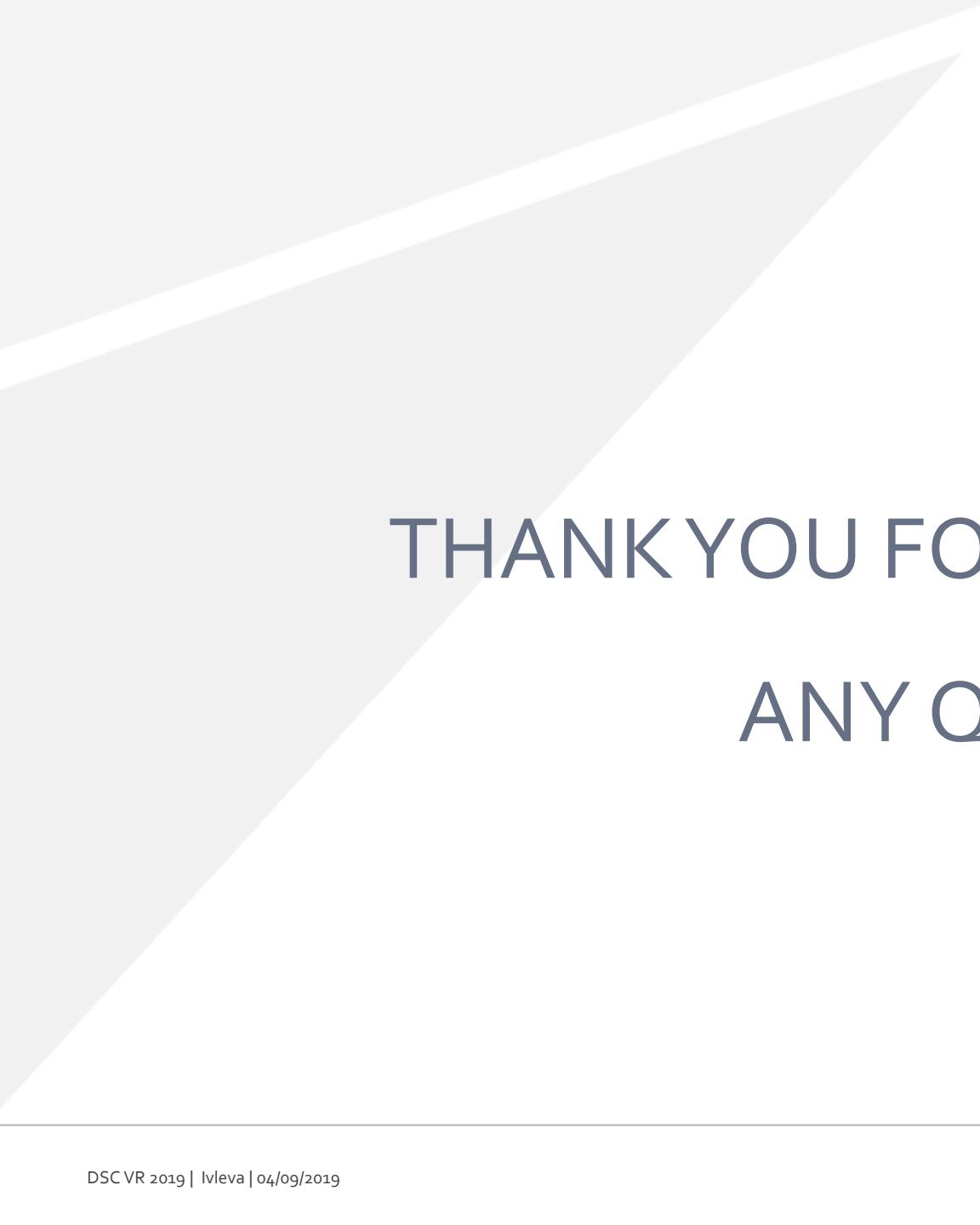
More interactions and tasks in VR

- Preliminary conversation and safety instructions also in VR
- Pick up the car keys at the information desk
- Interact with human avatars

Explore other aspects: e.g. distance estimation

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THANK YOU FOR YOUR ATTENTION!  
ANY QUESTIONS?