

Summer Semester 2014

## Assignment on Advanced Computer Graphics - Sheet 6

Due Date 30. 06. 2014 11:59pm  
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### Exercise 1 (Procedural Brick Texture, 4 Credits)

In the Advanced Shader Techniques lecture a procedural brick texture was introduced:

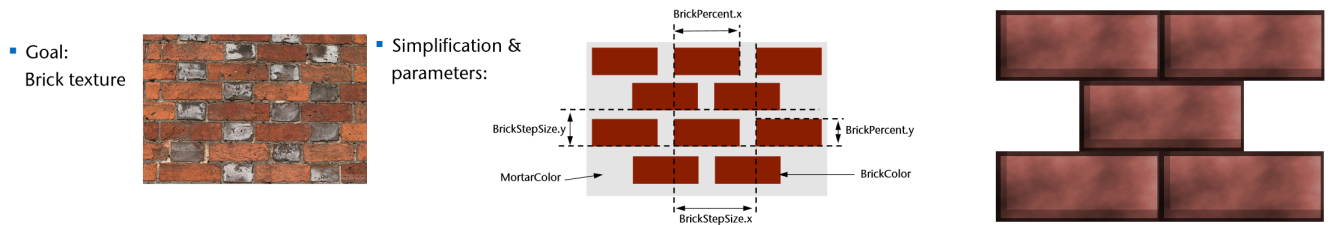


Figure 1: Procedural brick texture approach from the lecture.

Re-implement the idea in Ogre within the given framework:

- Implement the functions `BrickFramework::generateMortar` and `BrickFramework::generateBrick`, which should generate the texture for the mortar and brick respectively. For the brick and mortar texture use the `SimpleNoise` class or your favourite noise library to generate some interesting brickwalls. Also add some 'shadow' directly on the brick texture. Assume, that no lighting/shader/bump mapping/displacement/parallax mapping will be used. See the example picture for some reference of the bricks.
- Use `BrickFramework::generateBrickTexture(double BrickStepSizeX, double BrickPercentX, double BrickStepSizeY, double BrickPercentY, Ogre::TexturePtr MortarColor, Ogre::TexturePtr BrickColor)` to generate a brick texture. This function takes as input the result from your implemented `BrickFramework::generateMortar` and `BrickFramework::generateBrick` functions.
- The generated texture should be applied to the given `Ogre::Plane`, document your results with some screenshots.
- As an extension, come up with a suitable algorithm which generates circle-based bricks. Describe your algorithm (inputs, constraints, etc.) and additionally document your results with screenshots.

## Exercise 2 (Culling Maths in 2D, 4 Credits)

- Given two 2D objects  $O_1, O_2$  each with three triangles  $t_{11}((7/4), (9/2), (9/4))$   $t_{12}((9/2), (9/4), (11/4))$   $t_{13}((9/4), (9/6), (11/4))$  and  $t_{21}((0/4), (1/4), (1/2))$   $t_{22}((1/2), (1/4), (3/4))$   $t_{23}((1/2), (3/4), (3/0))$ . Compute the bounding spheres of  $O_1, O_2$  and determine, whether or not  $O_1, O_2$  are visible inside the view frustum (simplified as a box)  $F : Min = (1, 1), Max = (6, 4)$ .
- Following your bounding sphere visibility test result, determine for all triangles of a potentially visible  $O$  whether they are really inside the frustum or not. In order to do so, check for all triangles whether they are completely inside or completely outside the frustum. If a triangle is only partially visible, determine the remaining clipped triangle(s) with their vertices.
- Do a sketch of the complete scene ( $O_1, O_2, Frustum$ ) and mark the rendered triangles. Write down the calculations needed to compute the culling for  $O_1, O_2$ .

## Exercise 3 (Cube Maps, 2 Credits)

Given the  $(s, t, r)$  texture coordinates of a vertex, assume that  $|s|$  is the largest component by value, i.e., OpenGL will have to project  $(s, t, r)$  onto the side  $x = 1$  of the unit cube (which is the parameter domain for cube maps).

Write down the GPU calculations needed to compute the  $(u, v)$  pair on that cube side.